

ON TOPOLOGICAL CLOSED GRAPHS IN THE NEW FORM

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ABSTRACT. The aim of this paper is to introduce \tilde{g}_α -closed graphs and strongly \tilde{g}_α -closed graphs using \tilde{g}_α -open sets and derive the relation between them. We also derive the basic properties of the strongly \tilde{g}_α -closed graphs in terms of \tilde{g}_α -continuous, weakly \tilde{g}_α -continuous, \tilde{g}_α -irresolute, completely \tilde{g}_α -continuous and almost \tilde{g}_α -irresolute functions. As an application we introduce \tilde{g}_α -Hausdorff spaces, strongly G-closed spaces and present some of their properties with \tilde{g}_α -closed graphs.

1. INTRODUCTION

Jafari et al.[1] introduced \tilde{g}_α -closed sets in topological spaces and proved that the class of \tilde{g}_α -closed sets form a topology. Long[5] introduced closed graphs and Noiri introduced[4] strongly closed graphs. In this paper we have introduced \tilde{g}_α -closed graphs and strongly \tilde{g}_α -closed graphs and established the relationship between them. We have derived some of the properties of strongly \tilde{g}_α -closed graphs with the help of different types of \tilde{g}_α -maps. As an application we have introduced \tilde{g}_α -Hausdorff spaces and strongly G-closed spaces.

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2. PRELIMINARIES

We list some definitions which are useful in the following sections. The interior and the closure of a subset A of (X, τ) are denoted by $Int(A)$ and $Cl(A)$, respectively. Throughout the present paper (X, τ) and (Y, σ) (or X and Y) represent topological spaces on which no separation axiom is defined, unless otherwise mentioned.

Definition 2.1. A subset A of a space X is called

- (i) a semi-open set [4] if $A \subseteq Cl(Int(A))$
- (ii) an α -open set [6] if $A \subseteq Int(Cl(Int(A)))$
- (iii) regular open set [8] if $A = Int(Cl(A))$

The complement of a semi-open (resp α -open and regular open) set is called a semi-closed (resp. α -closed and regular closed) set. The α -closure[6] (resp semi-closure[4]) of a subset A of X is denoted by $\alpha Cl(A)$ (resp $sCl(A)$) and is defined to be the intersection of all α -closed sets (resp. semi-closed sets) containing A . A subset A of a topological space (X, τ) is α -closed (resp. semi-closed) if and only if $\alpha Cl(A) = A$ (resp $sCl(A) = A$). The collection of all semi-open sets, α -open sets and regular open sets are denoted by $SO(X)$, $\alpha O(X)$ and $RO(X)$ respectively. The collection of all semi-closed sets, α -closed sets and regular closed sets are denoted as $SC(X)$, $\alpha C(X)$ and $RC(X)$ respectively.

Definition 2.2. A subset A of a topological space (X, τ) is called

- (i) an ω -closed set [11] if $Cl(A) \subseteq U$ whenever $A \subseteq U$ and U is semi-open in (X, τ) ,
- (ii) a *g -closed set [15] if $Cl(A) \subseteq U$ whenever $A \subseteq U$ and U is ω -open in (X, τ) ,
- (iii) a $^\#g$ -semi-closed set (briefly $^\#gs$ -closed)[16] if $sCl(A) \subseteq U$ whenever $A \subseteq U$ and U is *g -open in (X, τ) ,

(iv) \tilde{g}_α -closed set[2] if $\alpha Cl(A) \subseteq U$ whenever $A \subseteq U$ and U is $\#gs$ -open in (X, τ) and

(v) \tilde{g} -closed set[1] if $Cl(A) \subseteq U$ whenever $A \subseteq U$ and U is $\#gs$ -open in (X, τ)

The complement of ω -closed(resp $\ast g$ -closed, $\#gs$ -closed, \tilde{g}_α -closed and \tilde{g} -closed)set is said to be ω -open(resp $\ast g$ -open, $\#gs$ -open, \tilde{g}_α -open and \tilde{g} -open). The collection of all \tilde{g}_α -open sets and \tilde{g}_α -closed sets are denoted by $\tilde{G}_\alpha O(X)$ and $\tilde{G}_\alpha C(X)$ respectively.

Theorem 2.1 (2). (i) Every open set is \tilde{g}_α -open but not conversely.

(ii) Every α -open set is \tilde{g}_α -open but not conversely.

(iii) Every \tilde{g} -open set is \tilde{g}_α -open but not conversely.

(iv) Every \tilde{g}_α -open set is $g\alpha(\alpha g)$ -open but not conversely.

(v) Every \tilde{g}_α -open set is $sg(gs\text{-open})$ -open but not conversely .

Definition 2.3. Let (X, τ) be a topological space and E be subset of X . We define \tilde{g}_α -Interior of E denoted by $\tilde{g}_\alpha\text{-Int}(E)$ to be the union of all \tilde{g}_α -open sets contained in E . [2]

Definition 2.4. Let x be a point of (X, τ) and V be a subset of X . Then V is called a \tilde{g}_α -neighbourhood of x in (X, τ) if there exists a \tilde{g}_α -open set U of (X, τ) such that $x \in U \subseteq V$. [14]

Proposition 2.1 (2). For any two subsets A and B of (X, τ)

$$(1) \tilde{g}_\alpha\text{-Int}(A \cap B) = \tilde{g}_\alpha\text{-Int}(A) \cap \tilde{g}_\alpha\text{-Int}(B)$$

$$(2) \tilde{g}_\alpha\text{-Int}(A \cup B) \subseteq \tilde{g}_\alpha\text{-Int}(A) \cup \tilde{g}_\alpha\text{-Int}(B)$$

$$(3) \text{ If } A \subseteq B \text{ then } \tilde{g}_\alpha\text{-Int}(A) \subseteq \tilde{g}_\alpha\text{-Int}(B)$$

$$(4) \tilde{g}_\alpha\text{-Int}(X) = X.$$

$$(5) \tilde{g}_\alpha\text{-Int}(\phi) = \phi.$$

Definition 2.5 (2). Let (X, τ) be a topological space and $B \subseteq X$. We define the \tilde{g}_α -closure of B (briefly $\tilde{g}_\alpha\text{-Cl}(B)$) to be the intersection of all \tilde{g}_α -closed sets containing B which is denoted by $\tilde{g}_\alpha\text{-Cl}(B) = \bigcap \{A : B \subseteq A \text{ and } A \in \tilde{G}_\alpha C(X, \tau)\}$.

Lemma 2.1. For any $B \subseteq X$, $B \subseteq \tilde{g}_\alpha\text{-Cl}(B) \subseteq \text{Cl}(B)$ [2]

Theorem 2.2. The \tilde{g}_α -closure is a Kuratowski closure operator on X . [2]

Proposition 2.2 (2). Let (X, τ) be a topological space and $B \subseteq A$. The following properties hold. i) $\tilde{g}_\alpha\text{-Cl}(B)$ is the smallest \tilde{g}_α -closed set containing B .

ii) B is \tilde{g}_α -closed if and only if $\tilde{g}_\alpha\text{-Cl}(B) = B$

Definition 2.6. A function $f : (X, \tau) \rightarrow (Y, \sigma)$ is called

- (i) \tilde{g}_α -continuous [14] if $f^{-1}(V)$ is a \tilde{g}_α -open set (X, τ) for each open set V of (Y, σ) ,
- (ii) \tilde{g}_α -irresolute [12] if $f^{-1}(V)$ is a \tilde{g}_α -open set of (X, τ) for each \tilde{g}_α -open set V of (Y, σ) ,

Proposition 2.3 (14). A function $f : (X, \tau) \rightarrow (Y, \sigma)$ is said to be \tilde{g}_α -continuous if for each $x \in X$ and every $V \in O(Y, f(x))$ there exist a $U \in \tilde{G}_\alpha O(X, x) \ni f(U) \subseteq V$.

Proposition 2.4. Every \tilde{g}_α -irresolute function is \tilde{g}_α -continuous. [12]

Definition 2.7 (5). Let $f : (X, \tau) \rightarrow (Y, \sigma)$ be any function. Then the subset $G(f) = \{(x, f(x)) : x \in X\}$ of the product space $(X \times Y, \tau \times \sigma)$ is called the graph of f .

Definition 2.8 (5). Let (X, τ) and (Y, σ) are topological spaces. A function $f : (X, \tau) \rightarrow (Y, \sigma)$ is said to have the closed graph if its graph $G(f)$ is closed in the product space $(X \times Y, \tau \times \sigma)$.

Definition 2.9 (7). Let (X, τ) and (Y, σ) are topological spaces. A function $f : (X, \tau) \rightarrow (Y, \sigma)$ is said to have the strongly closed graph if for each $(x, y) \in X \times Y - G(f)$, there exist $U \in O(X, x), V \in O(Y, y)$ such that $U \times Cl(V) \cap G(f) = \phi$.

Remark 1. The set of all open sets containing the point x is denoted by $O(X, x)$. Similarly $\tilde{G}_\alpha O(X, x)$ and $\alpha O(X, x)$ denote the set of all \tilde{g}_α -open sets and α -open sets containing the point x respectively. Also $RO(X) = \{V \in RO(X) / x \in V \text{ for } x \in X\}$.

Lemma 2.2 (5). A function $f : (X, \tau) \rightarrow (Y, \sigma)$ has a closed graph if for each $(x, y) \in X \times Y - G(f)$, there exist $U \in O(X, x), V \in O(Y, y)$ such that $f(U) \cap V = \phi$.

Lemma 2.3 (7). A function $f : (X, \tau) \rightarrow (Y, \sigma)$ has a strongly closed graph if for each $(x, y) \in X \times Y - G(f)$, there exist $U \in O(X, x), V \in O(Y, y)$ such that $f(U) \cap Cl(V) = \phi$.

Definition 2.10 (10). A space (X, τ) is called

- (i) \tilde{g} - T_0 if for every pair of distinct points x, y in X there exists a \tilde{g} -open set U containing one of the points but not the other.
- (ii) \tilde{g} - T_1 if for every pair of distinct points x, y in X there exists a \tilde{g} -open set U containing x but not y and a \tilde{g} -open set V containing y but not x .
- (iii) \tilde{g} - T_2 if for every pair of distinct points x, y in X there exist disjoint \tilde{g} -open sets U and V containing x and y respectively.[10]

3. \tilde{g}_α -CLOSED GRAPHS

Definition 3.1. A function $f : (X, \tau) \rightarrow (Y, \sigma)$ is said to have a \tilde{g}_α -closed graph if for each $(x, y) \in X \times Y - G(f)$, there exist $U \in \tilde{G}_\alpha O(X, x), V \in \tilde{G}_\alpha O(Y, y)$ such that $U \times V \cap G(f) = \phi$

Lemma 3.1. Let $f : (X, \tau) \rightarrow (Y, \sigma)$ be a function then the graph $G(f)$ is \tilde{g}_α -closed in $X \times Y$ if and only if for each $(x, y) \in X \times Y - G(f)$, there exist $U \in \tilde{G}_\alpha O(X, x), V \in \tilde{G}_\alpha O(Y, y)$ such that $f(U) \cap V = \phi$

Proof. It follows from the definition. \square

Definition 3.2. A space (X, τ) is called

- (i) \tilde{g}_α - T_0 if for every pair of distinct points x, y in X there exists a \tilde{g}_α -open set U containing one of the points but not the other.
- (ii) \tilde{g}_α - T_1 if for every pair of distinct points x, y in X there exists a \tilde{g}_α -open set U containing x not y and a \tilde{g}_α -open set V containing y but not x .
- (iii) \tilde{g}_α - T_2 if for every pair of distinct points x, y in X there exist disjoint \tilde{g}_α -open sets U and V containing x and y respectively.

Remark 2. Every \tilde{g} - T_i -space is \tilde{g}_α - T_i -space for $i = 0, 1, 2$.

Example 3.1. Let $X = \{a, b, c\}, \tau = \{\phi, X, \{a, b\}\}$. Here X is a \tilde{g}_α - T_0 -space but not a \tilde{g} - T_0 -space.

Theorem 3.1. If $f : (X, \tau) \rightarrow (Y, \sigma)$ is an injective function with the \tilde{g}_α -closed graph $G(f)$ then X is \tilde{g}_α - T_1

Proof. Let x and y be two distinct points of X then $f(x) \neq f(y)$. Thus $(x, f(y)) \in X \times Y - G(f)$. But $G(f)$ is \tilde{g}_α -closed. So there exist \tilde{g}_α -open sets U and V containing x and $f(y)$ respectively such that $f(U) \cap V = \phi$. Hence $y \notin U$. Similarly there exist \tilde{g}_α -open sets M and N containing y and $f(x)$ such that $f(M) \cap N = \phi$. Hence $x \notin M$. It follows that X is \tilde{g}_α - T_1 \square

Theorem 3.2. If $f : (X, \tau) \rightarrow (Y, \sigma)$ is a surjective function with the \tilde{g}_α -closed graph $G(f)$ then Y is \tilde{g}_α - T_1 .

Proof. Let y and z be two distinct points of Y . Since f is surjective there exist a point x in X such that $f(x) = z$. Therefore $(x, y) \notin G(f)$, by lemma 3.2 there exist \tilde{g}_α -open sets U and V containing x and y respectively such that $f(U) \cap V = \phi$. It follows that $z \notin V$. Similarly there exist $w \in X$ such that $f(w) = y$. Hence $(w, z) \notin G(f)$.

Similarly there exist \tilde{g}_α -open sets M and N containing w and z respectively such that such that $f(M) \cap N = \phi$. Thus $y \notin N$. Hence the space Y is \tilde{g}_α - T_1 . \square

Definition 3.3. A function $f : (X, \tau) \rightarrow (Y, \sigma)$ is said to be weakly \tilde{g}_α -continuous if for each $x \in X$ and each open set V of Y containing $f(x)$, there exists a \tilde{g}_α -open set U in X containing x such that $f(U) \subseteq \tilde{g}_\alpha\text{-Cl}(V)$

Remark 3. Any \tilde{g}_α -continuous function is weakly \tilde{g}_α -continuous.

Example 3.2. Let $X = \{a, b, c\}, Y = \{p, q, r\}, \tau = \{\phi, X, \{a\}, \{b, c\}\}, \sigma = \{\phi, Y, \{p\}, \{q\}, \{p, q\}, \{p, r\}\}$. The function $f : (X, \tau) \rightarrow (Y, \sigma)$ is defined as $f(a) = p, f(b) = q, f(c) = r$. The function f is weakly \tilde{g}_α -continuous but not \tilde{g}_α -continuous.

Theorem 3.3. If a function $f : (X, \tau) \rightarrow (Y, \sigma)$ is weakly \tilde{g}_α -continuous and Y is Hausdorff, then $G(f)$ is \tilde{g}_α -closed.

Proof. Suppose that $(x, y) \notin G(f)$ then $f(x) \neq y$. Since Y is Hausdorff, there exist open sets W and V such that $f(x) \in W, y \in V$ and $W \cap V = \phi$. It follows that $\tilde{g}_\alpha\text{-Cl}(W) \cap V = \phi$. Since f is weakly \tilde{g}_α -continuous there exist $U \in \tilde{G}_\alpha O(X, x)$ such that $f(U) \subseteq \tilde{g}_\alpha\text{-Cl}(W)$. Hence $f(U) \cap V = \phi$. Thus $G(f)$ is \tilde{g}_α -closed. \square

Corollary 3.1. If a function $f : (X, \tau) \rightarrow (Y, \sigma)$ is \tilde{g}_α -continuous and Y is Hausdorff, then $G(f)$ is \tilde{g}_α -closed.

Theorem 3.4. If a function $f : (X, \tau) \rightarrow (Y, \sigma)$ has a \tilde{g}_α -closed graph then for each $x \in X, \{f(x)\} = \bigcap_{A \in \tilde{G}_\alpha O(X, x)} \tilde{g}_\alpha\text{-Cl}(f(A))$

Proof. Suppose that $y \neq f(x)$ and $y \in \bigcap_{A \in \tilde{G}_\alpha O(X, x)} \tilde{g}_\alpha\text{-Cl}(f(A))$. Then $y \in \tilde{g}_\alpha\text{-Cl}(f(A))$ for each $x \in A \in \tilde{G}_\alpha O(X, x)$. This implies that for each \tilde{g}_α -open set B containing y , $B \cap f(A) \neq \phi$ (By lemma 8.3[14]). Since $(x, y) \notin G(f)$ and $G(f)$ is a \tilde{g}_α -closed graph, this is a contradiction. Hence the result. \square

Definition 3.4. A function $f : (X, \tau) \rightarrow (Y, \sigma)$ is said to be strongly \tilde{g}_α -open if the image of every \tilde{g}_α -open set in X is \tilde{g}_α -open in Y .

Theorem 3.5. If $f : (X, \tau) \rightarrow (Y, \sigma)$ is a surjective strongly \tilde{g}_α -open function with \tilde{g}_α -closed graph $G(f)$ then Y is $\tilde{g}_\alpha - T_2$.

Proof. Let y_1, y_2 be distinct points of Y . Since f is surjective $f(x) = y_1$ for some $x \in X$ and $(x, y_2) \in X \times Y - G(f)$. This implies that there exist a \tilde{g}_α -open set A of X and a \tilde{g}_α -open set B of Y such that $(x, y_2) \in A \times B$ and $(A \times B) \cap G(f) = \phi$. We have $f(A) \cap B = \phi$. Since f is strongly \tilde{g}_α -open then $f(A)$ is \tilde{g}_α -open such that $f(x) = y_1 \in f(A)$. Thus Y is $\tilde{g}_\alpha - T_2$. \square

Theorem 3.6. If $f : (X, \tau) \rightarrow (Y, \sigma)$ is a \tilde{g}_α -continuous injective function and Y is T_2 then X is $\tilde{g}_\alpha - T_2$.

Proof. Let x and y in X be any pair of distinct points. Then there exist disjoint open sets U and V in Y such that $f(x) \in U, f(y) \in V$. Since f is \tilde{g}_α -continuous, $f^{-1}(U), f^{-1}(V)$ are \tilde{g}_α -open in X containing x and y respectively. We have $f^{-1}(U) \cap f^{-1}(V) = \phi$. Thus X is $\tilde{g}_\alpha - T_2$. \square

4. STRONGLY \tilde{g}_α -CLOSED GRAPHS

Definition 4.1. A function $f : (X, \tau) \rightarrow (Y, \sigma)$ is said to have a strongly \tilde{g}_α -closed graph if and only if for each $(x, y) \in X \times Y - G(f)$, there exist $U \in \tilde{G}_\alpha O(X, x), V \in \tilde{G}_\alpha O(Y, y)$ such that $U \times \tilde{g}_\alpha - Cl(V) \cap G(f) = \phi$.

Lemma 4.1. A function $f : (X, \tau) \rightarrow (Y, \sigma)$ has a strongly \tilde{g}_α -closed graph if and only for each $(x, y) \in X \times Y - G(f)$, there exist $U \in \tilde{G}_\alpha O(X, x), V \in \tilde{G}_\alpha O(Y, y)$ such that $f(U) \cap \tilde{g}_\alpha - Cl(V) = \phi$.

Remark 4. Any strongly \tilde{g}_α -closed graph is a \tilde{g}_α -closed graph but not conversely.

Example 4.1. Let $X = \{a, b, c\}, \tau = \{\phi, X, \{a, b, c\}\}, Y = \{p, q, r\}, \sigma = \{\phi, Y, \{p, q\}\}$. The function f is defined as $f(a) = f(c) = p, f(b) = q$. The function f has a \tilde{g}_α -closed graph but not a strongly \tilde{g}_α -closed graph.

Remark 5. If (X, τ) is \tilde{g}_α - T_i then it is \tilde{g}_α - T_{i-1} for $i=1,2$.

Example 4.2. Let $X = \{a, b, c\}, \tau = \{\phi, X, \{a, b, c\}\}$. The space X is \tilde{g}_α - T_0 but not \tilde{g}_α - T_1 and \tilde{g}_α - T_2 .

Theorem 4.1. If $f : (X, \tau) \rightarrow (Y, \sigma)$ is \tilde{g}_α -irresolute and Y is \tilde{g}_α - T_2 then $G(f)$ is strongly \tilde{g}_α -closed.

Proof. Let $(x, y) \in X \times Y - G(f)$. Since Y is \tilde{g}_α - T_2 there exist a $V \in \tilde{G}_\alpha O(Y, y)$ such that $f(x) \notin \tilde{g}_\alpha$ - $Cl(V)$. Then $Y - \tilde{g}_\alpha$ - $Cl(V) \in \tilde{G}_\alpha O(Y, f(x))$. Since f is \tilde{g}_α -irresolute, there exist a $U \in \tilde{G}_\alpha O(X, x) \ni f(U) \subseteq Y - \tilde{g}_\alpha$ - $Cl(V)$ (By theorem 3.11[14]) then $f(U) \cap \tilde{g}_\alpha$ - $Cl(V) = \phi$. Hence $G(f)$ is strongly \tilde{g}_α -closed. \square

Theorem 4.2. If $f : (X, \tau) \rightarrow (Y, \sigma)$ is \tilde{g}_α -open and has a closed graph $G(f)$ then $G(f)$ is strongly \tilde{g}_α -closed.

Proof. Let $(x, y) \in X \times Y - G(f)$. Since $G(f)$ is closed there exist $U \in O(X, x), V \in O(Y, y)$ such that $f(U) \cap V = \phi$ —(i). Since f is \tilde{g}_α -open $f(U) \in \tilde{G}_\alpha O(Y)$. From (i) we get $V \subseteq (f(U))^c$ and $f(U)^c$ is \tilde{g}_α -closed in Y . Therefore \tilde{g}_α - $Cl(V) \subseteq (f(U))^c$ and hence $f(U) \cap \tilde{g}_\alpha$ - $Cl(V) = \phi$. Hence $G(f)$ is strongly \tilde{g}_α -closed. \square

Theorem 4.3. If $f : (X, \tau) \rightarrow (Y, \sigma)$ is surjective and has a strongly \tilde{g}_α -closed graph $G(f)$ then Y is \tilde{g}_α - T_2 .

Proof. Let $y_1 \neq y_2 \in Y$. Since f is surjective there exist $x_1 \in X \ni f(x_1) = y_1$. Now $(x_1, y_2) \in X \times Y - G(f)$. Since $G(f)$ is strongly \tilde{g}_α -closed it implies that there exist $U \in \tilde{G}_\alpha O(X, x_1), V \in \tilde{G}_\alpha O(Y, y_2) \ni f(U) \cap \tilde{g}_\alpha$ - $Cl(V) = \phi$ which implies that

$y_1 \notin \tilde{g}_\alpha\text{-Cl}(V)$. This means that there exist $W \in \tilde{G}_\alpha O(Y, y_1) \ni W \cap V = \phi$. So Y is $\tilde{g}_\alpha\text{-}T_2$. \square

Theorem 4.4. *A space X is $\tilde{g}_\alpha\text{-}T_2$ if and only if the identity function $i : X \rightarrow X$ has a strongly $\tilde{g}_\alpha\text{-closed}$ graph.*

Proof. Necessity. Let X be $\tilde{g}_\alpha\text{-}T_2$. Since the identity function is $\tilde{g}_\alpha\text{-irresolute}$ by theorem 4.1 $G(i)$ is strongly $\tilde{g}_\alpha\text{-closed}$.

Sufficiency. Let $G(i)$ be strongly $\tilde{g}_\alpha\text{-closed}$. Since f is surjective by theorem 4.3 X is $\tilde{g}_\alpha\text{-}T_2$. \square

Theorem 4.5. *If $f : (X, \tau) \rightarrow (Y, \sigma)$ is a bijective function with strongly $\tilde{g}_\alpha\text{-closed}$ graph then both X and Y are $\tilde{g}_\alpha\text{-}T_1$*

Proof. It follows from the Theorems 4.3 and 3.1. \square

Definition 4.2. A function $f : (X, \tau) \rightarrow (Y, \sigma)$ is said to be weakly $\tilde{g}_\alpha\text{-irresolute}$ if for each point x in X and each $V \in \tilde{G}_\alpha O(Y, f(x))$ there exists $U \in \tilde{G}_\alpha O(X, x)$ such that $f(U) \subseteq \tilde{g}_\alpha\text{-Cl}(V)$.

Remark 6. Any $\tilde{g}_\alpha\text{-irresolute}$ function is weakly $\tilde{g}_\alpha\text{-irresolute}$.

Example 4.3. Let $X = Y = \{a, b, c\}, \tau = \{\phi, X, \{a, c\}, \{b\}\}, \sigma = \{\phi, Y, \{a, b\}\}$. The function f is the identity function. Here f is weakly $\tilde{g}_\alpha\text{-irresolute}$ but not $\tilde{g}_\alpha\text{-irresolute}$.

Theorem 4.6. *If $f : (X, \tau) \rightarrow (Y, \sigma)$ is a weakly $\tilde{g}_\alpha\text{-irresolute}$ injective function with strongly $\tilde{g}_\alpha\text{-closed}$ graph $G(f)$ then X is $\tilde{g}_\alpha\text{-}T_2$*

Proof. Since f is injective for any pair of distinct points $x_1, x_2 \in X, f(x_1) \neq f(x_2)$. Therefore $(x_1, f(x_2)) \in X \times Y - G(f)$. Since $G(f)$ is strongly $\tilde{g}_\alpha\text{-closed}$ there exist $U \in \tilde{G}_\alpha O(X, x_1), V \in \tilde{G}_\alpha O(Y, f(x_2))$ such that $f(U) \cap \tilde{g}_\alpha\text{-Cl}(V) = \phi$ and hence $U \cap f^{-1}(\tilde{g}_\alpha\text{-Cl}(V)) = \phi$ which gives $f^{-1}(\tilde{g}_\alpha\text{-Cl}(V)) \subseteq X - U$. Since f is weakly

\tilde{g}_α -irresolute, there exist $W \in \tilde{G}_\alpha O(X, x_2) \ni f(W) \subseteq \tilde{g}_\alpha\text{-Cl}(V)$. Hence $W \subseteq f^{-1}(\tilde{g}_\alpha\text{-Cl}(V)) \subseteq X - U$ which implies that $W \cap U = \phi$. Hence X is $\tilde{g}_\alpha\text{-}T_2$. \square

Corollary 4.1. *If $f : (X, \tau) \rightarrow (Y, \sigma)$ is a \tilde{g}_α -irresolute function with strongly \tilde{g}_α -closed graph then $G(f)$ then X is $\tilde{g}_\alpha\text{-}T_2$*

Definition 4.3. A function $f : (X, \tau) \rightarrow (Y, \sigma)$ is said to be almost \tilde{g}_α -irresolute if for each x in X and each \tilde{g}_α neighbourhood V of $f(x)$, $\tilde{g}_\alpha\text{-Cl}(f^{-1}(V))$ is a \tilde{g}_α neighbourhood of x .

Remark 7. Every \tilde{g}_α -irresolute function is almost \tilde{g}_α -irresolute.

Example 4.4. *Let $X = Y = \{a, b, c\}, \tau = \{\phi, X, \{a, b\}, \{c\}\}, \sigma = \{\phi, Y, \{a, b\}\}$. The function f is the identity function. Here f is almost \tilde{g}_α -irresolute but not \tilde{g}_α -irresolute.*

Theorem 4.7. *If a function $f : (X, \tau) \rightarrow (Y, \sigma)$ is almost \tilde{g}_α -irresolute, injective with strongly \tilde{g}_α -closed graph then X is $\tilde{g}_\alpha\text{-}T_2$.*

Proof. As in Theorem 4.6 we get $f(U) \cap \tilde{g}_\alpha\text{-Cl}(V) = \phi$ and hence $U \cap f^{-1}(\tilde{g}_\alpha\text{-Cl}((V))) = \phi$ which implies that $f^{-1}(\tilde{g}_\alpha\text{-Cl}((V))) \subseteq X - U$. Since $X - U$ is a \tilde{g}_α -closed set containing $f^{-1}(\tilde{g}_\alpha\text{-Cl}((V)))$ and any $\tilde{g}_\alpha\text{-Cl}(f^{-1}(\tilde{g}_\alpha\text{-Cl}((V))))$ is the smallest \tilde{g}_α -closed containing $f^{-1}(\tilde{g}_\alpha\text{-Cl}((V)))$, we have $\tilde{g}_\alpha\text{-Cl}(f^{-1}(\tilde{g}_\alpha\text{-Cl}((V)))) \subseteq X - U$. Since f is almost \tilde{g}_α -irresolute $\tilde{g}_\alpha\text{-Cl}(f^{-1}(\tilde{g}_\alpha\text{-Cl}((V))))$ is a \tilde{g}_α neighbourhood of x_2 . This implies that there exist $H \in \tilde{G}_\alpha O(X, x_2)$ such that $H \subseteq \tilde{g}_\alpha\text{-Cl}(f^{-1}(\tilde{g}_\alpha\text{-Cl}((V)))) \subseteq X - U$ which implies that $U \cap H = \phi$. Thus X is $\tilde{g}_\alpha\text{-}T_2$. \square

Theorem 4.8. *If a function $f : (X, \tau) \rightarrow (Y, \sigma)$ is almost \tilde{g}_α -irresolute, bijective with strongly \tilde{g}_α -closed graph then both X and Y are $\tilde{g}_\alpha\text{-}T_2$.*

Proof. It follows from Theorems 4.5 and 4.7. \square

Definition 4.4. A function $f : (X, \tau) \rightarrow (Y, \sigma)$ is said to be nearly \tilde{g}_α -continuous if and only if for each x in X and for each $V \in RO(Y, f(x))$ there exist a $U \in \tilde{G}_\alpha O(X, x)$ such that $f(U) \subseteq V$.

Remark 8. Every \tilde{g}_α -continuous function is nearly \tilde{g}_α -continuous.

Example 4.5. Let $X = Y = \{a, b, c\}, \tau = \{\phi, X, \{a\}\}, \sigma = \{\phi, Y, \{a, b\}\}$. The function f is the identity function. Here f is \tilde{g}_α -irresolute but not nearly \tilde{g}_α -irresolute.

Theorem 4.9. If $f : (X, \tau) \rightarrow (Y, \sigma)$ is nearly \tilde{g}_α -continuous and Y is T_2 , then $G(f)$ is strongly \tilde{g}_α -closed.

Proof. Let $(x, y) \in X \times Y - G(f)$. Since Y is T_2 there exist an open set V in Y containing y such that $f(x) \notin Cl(V)$. $Cl(V)$ is a regular closed set in Y . So $Y - Cl(V) \in RO(Y, f(x))$. By the nearly \tilde{g}_α -continuity of f there exist $U \in \tilde{G}_\alpha O(X, x)$ such that $f(U) \subseteq Y - Cl(V)$ hence $f(U) \cap Cl(V) = \phi$. Hence $f(U) \cap \tilde{g}_\alpha - Cl(V) = \phi$. \square

Corollary 4.2. If $f : (X, \tau) \rightarrow (Y, \sigma)$ is \tilde{g}_α -continuous and Y is T_2 , then $G(f)$ is strongly \tilde{g}_α -closed.

5. APPLICATIONS

Definition 5.1. A space (X, τ) is called strongly G -closed if every \tilde{g}_α -open cover of X has a finite subfamily such that the union of their \tilde{g}_α -closures cover X .

Definition 5.2. A subset A of X is said to be strongly G -closed relative to X , if every cover of A by \tilde{g}_α -open sets of X has a finite subfamily such that the union of their \tilde{g}_α -closures cover X .

Definition 5.3. A subset A of (X, τ) is said to be \tilde{g}_α -clopen if A is both \tilde{g}_α -open and \tilde{g}_α -closed.

Lemma 5.1. *Every \tilde{g}_α -clopen subset of a strongly G -closed space X is strongly G -closed relative to X .*

Proof. Let A be any \tilde{g}_α -clopen subset of a strongly G -closed space X . Let $\{G_\alpha : \alpha \in I\}$ be any cover of A by \tilde{g}_α -open sets in X . Then $\Omega = \{G_\alpha : \alpha \in I\} \cup \{A^c\}$ is a cover of X by \tilde{g}_α -open sets in X . Because of the strong G closedness of X there exist a finite subfamily $E = \{G_{\alpha_i} : i = 1, 2, \dots, n\} \cup \{A^c\}$ of Ω that covers X . Since A is \tilde{g}_α -clopen we find that $\{\tilde{g}_\alpha\text{-Cl}(G_{\alpha_i}) : i = 1, 2, \dots, n\}$ covers A . Hence A is strongly G -closed relative to X . \square

Definition 5.4. A space (X, τ) is called extremally \tilde{g}_α -disconnected if the \tilde{g}_α closure of every \tilde{g}_α -open set is \tilde{g}_α -open.

Example 5.1. Let $X = \{a, b, c, d\}, \tau = \{\phi, X, \{b\}, \{a, b\}, \{b, c, d\}\}$. $\tilde{G}_\alpha O(X) = \{\phi, X, \{b\}, \{a, b\}, \{b, c\}, \{b, d\}, \{a, b, c\}, \{a, b, d\}, \{b, c, d\}\}$. The space X is extremally \tilde{g}_α -disconnected.

Theorem 5.1. *If Y is strongly G -closed and extremally \tilde{g}_α -disconnected and \tilde{g}_α - T_2 then the function $f : (X, \tau) \rightarrow (Y, \sigma)$ with $G(f)$ strongly \tilde{g}_α -closed is weakly \tilde{g}_α -irresolute.*

Proof. Let $x \in X, V \in \tilde{G}_\alpha O(Y, f(x))$. Take any $y \in Y - \tilde{g}_\alpha\text{-Cl}(V)$. Then $(x, y) \in X \times Y - G(f)$. Since $G(f)$ is strongly \tilde{g}_α -closed, there exist $U_y \in \tilde{G}_\alpha O(X, x), V_y \in \tilde{G}_\alpha O(Y, y)$ such that $f(U_y) \cap \tilde{g}_\alpha\text{-Cl}(V_y) = \phi$ —(i). Since Y is \tilde{g}_α - T_2 , there exist $V_y \in \tilde{G}_\alpha O(Y, y)$ such that $f(x) \notin \tilde{g}_\alpha\text{-Cl}(V_y)$. Since Y is extremally \tilde{g}_α -disconnected implies the \tilde{g}_α -clopenness of $\tilde{g}_\alpha\text{-Cl}(V)$ and hence $Y - \tilde{g}_\alpha\text{-Cl}(V)$ is also \tilde{g}_α -clopen. Now $\{V_y : y \in Y - \tilde{g}_\alpha\text{-Cl}(V)\}$ is a cover of $Y - \tilde{g}_\alpha\text{-Cl}(V)$ by \tilde{g}_α -open sets in Y . By the Lemma 5.1 there exist a finite subfamily $\{V_{y_i} : i = 1, 2, \dots, n\}$ such that $Y - \tilde{g}_\alpha\text{-Cl}(V) \subseteq \bigcup_{i=1}^n \tilde{g}_\alpha\text{-Cl}(V_{y_i})$. Let $W = \bigcap_{i=1}^{i=n} U_{y_i}(x)$ where $U_{y_i}(x)$ are \tilde{g}_α -open sets in X satisfying

(i). Since finite intersection of \tilde{g}_α -open set is \tilde{g}_α -open[1], we have $f(W) \cap (Y - \tilde{g}_\alpha\text{-}Cl(V)) \subseteq f(\bigcap_{i=1}^n U_{y_i}(x)) \cap \bigcup_{i=1}^n (\tilde{g}_\alpha\text{-}Cl(V_{y_i})) = \bigcup_{i=1}^n (f(U_{y_i}(x)) \cap \tilde{g}_\alpha\text{-}Cl(V_{y_i})) = \phi$ by (i). Therefore $f(W) \subseteq \tilde{g}_\alpha\text{-}Cl(V)$ and hence f is weakly \tilde{g}_α -irresolute. \square

Corollary 5.1. *If Y is strongly G -closed, extremally \tilde{g}_α -disconnected space then the surjective function $f : (X, \tau) \rightarrow (Y, \sigma)$ with strongly \tilde{g}_α -closed graph is weakly \tilde{g}_α -irresolute.*

Proof. By the Theorem 4.3 Y is \tilde{g}_α - T_2 and by the Theorem 5.1 f is weakly \tilde{g}_α -irresolute. \square

Theorem 5.2. *Let the function $f : (X, \tau) \rightarrow (Y, \sigma)$ have a strongly \tilde{g}_α -closed graph $G(f)$. Then f satisfies the following property.*

P^* . *For each set A strongly G -closed relative to Y , $f^{-1}(A)$ is \tilde{g}_α -closed in X .*

Proof. If $f^{-1}(A)$ is not \tilde{g}_α -closed in X . Then there exists $x \in \tilde{g}_\alpha\text{-}Cl(f^{-1}(A)) - f^{-1}(A)$. Let $y \in A$. Then $(x, y) \in X \times Y - G(f)$. Since $G(f)$ is strongly \tilde{g}_α -closed, there exist $U_y(x) \in \tilde{G}_\alpha O(X, x)$, $V_y \in \tilde{G}_\alpha O(Y, y)$ such that $f(U_y(x)) \cap \tilde{g}_\alpha\text{-}Cl(V_y) = \phi$ —(i). $\{V_y : y \in A\}$ is a cover of A by \tilde{g}_α -open sets in Y . The strong G -closedness of A relative to Y implies the existence of \tilde{g}_α -open sets $V_{y_1}, V_{y_2}, \dots, V_{y_n}$ in Y such that $A \subseteq \bigcup_{i=1}^n \tilde{g}_\alpha\text{-}Cl(V_{y_i})$. Let $\{U_{y_i}(x) : i = 1, 2, \dots, n\}$ be the corresponding \tilde{g}_α -open sets in X satisfying (i). Let $U = \bigcap_{i=1}^n \{U_{y_i}(x) : i = 1, 2, \dots, n\}$. Then $U \in \tilde{G}_\alpha O(X, x)$. Since the finite intersection of \tilde{g}_α -open sets is \tilde{g}_α -open. We have, $f(U) \cap A \subseteq f(\bigcap_{i=1}^n U_{y_i}(x)) \cap (\bigcup_{i=1}^n \tilde{g}_\alpha\text{-}Cl(V_{y_i})) = \bigcup_{i=1}^n f(U_{y_i}(x)) \cap \tilde{g}_\alpha\text{-}Cl(V_{y_i}) = \phi$. But $x \in \tilde{g}_\alpha\text{-}Cl(f^{-1}(A)) \Rightarrow U \cap f^{-1}(A) \neq \phi$ a contradiction to our assumption to the above result. Hence our assumption is wrong. \square

Theorem 5.3. *For a \tilde{g}_α - T_2 space X , every strongly G -closed subset relative to X is \tilde{g}_α -closed.*

Proof. Let X be a \tilde{g}_α - T_2 space and A be a strongly G -closed subset relative to X . Let $x \in A$ and $y \in X - A$. Since X is \tilde{g}_α - T_2 and $x \neq y$ there exist $U_x \in \tilde{G}_\alpha O(X, x), V \in \tilde{G}_\alpha O(Y, y)$ such that $U_x \cap V = \phi \Rightarrow \tilde{g}_\alpha$ - $Cl(U_x) \cap V = \phi \Rightarrow y \notin \tilde{g}_\alpha$ - $Cl(U_x) \Rightarrow \tilde{g}_\alpha$ - $Cl(U_x) \subseteq X - \{y\}$. $\{U_x : x \in A\}$ is a cover of A by \tilde{g}_α -open sets in X . Since A is strongly G -closed relative to X there exist a finite subcover $\{U_{x_i} : i = 1, 2..n\}$ such that $A \subseteq \bigcup_{i=1}^n \tilde{g}_\alpha$ - $Cl(U_{x_i}) \subseteq \tilde{g}_\alpha$ - $Cl(\bigcup_{i=1}^n U_{x_i}) = \tilde{g}_\alpha$ - $Cl(U)$ where $U = \bigcup_{i=1}^n U_{x_i}$. Hence $y \notin \tilde{g}_\alpha$ - $Cl(U)$. If $y \in \tilde{g}_\alpha$ - $Cl(U)$ then $y \in \tilde{g}_\alpha$ - $Cl(\bigcup_{i=1}^n U_{x_i}) \Rightarrow (\bigcup_{i=1}^n U_{x_i}) \cap V \neq \phi \Rightarrow \bigcup_{i=1}^n (U_{x_i} \cap V) \neq \phi$ which is a contradiction. Therefore $A \subseteq \tilde{g}_\alpha$ - $Cl(U) \subseteq X - \{y\}$. Therefore $A = \bigcap_{y \in X-A} (X - \{y\}) = \bigcap_{y \in X-A} \tilde{g}_\alpha$ - $Cl(U_y)$. Hence A is \tilde{g}_α -closed in Y . \square

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