

M-Projective Curvature Tensor and Ricci-Bourguignon Soliton on Lorentzian β -Kenmotsu Manifold

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Received: Nov. 19, 2024

Accepted :April 10, 2025

Abstract: The prime object of the present article is to explore the characteristics of a Lorentzian β -Kenmotsu manifold ($\mathcal{M}_\beta$) admitting an $\mathbb{M}$ -projective curvature tensor. We derived characteristic theorems for $\mathcal{M}_\beta$ satisfying $\mathbb{M}$ -projectively φ -recurrent and pseudo-symmetric conditions. $\varphi - \mathbb{M}$ -projectively flat $\mathcal{M}_\beta$ is the subject of our next analysis. Additionally, we deal with the $\mathcal{M}_\beta$ satisfying $\mathbb{M}$ -projectively Ricci pseudo-symmetric condition. Next, we describe the $\mathcal{M}_\beta$ satisfying $R(\zeta, \mathcal{B}_3) \cdot \mathbb{M} = 0$ condition. Further, we discuss cyclic parallel Ricci tensor, $\mathcal{V}^\flat$ -parallel Ricci tensor and Ricci-Bourguignon soliton in $\mathcal{M}_\beta$. Finally, we have presented an example of an $\mathcal{M}_\beta$.

Keywords: Lorentzian β -Kenmotsu manifold ($\mathcal{M}_\beta$), $\mathbb{M}$ -projective curvature tensor, generalized $\mathcal{V}^\flat$ -Einstein manifold, Ricci pseudo-symmetric, and Ricci-Bourguignon soliton (RBS).

2010 Mathematics Subject Classification. 53C05; 53C15; 53C20; 53C25; 53D15; 53D10.

1 Introduction

If a smooth manifold possesses a Lorentzian metric g and a symmetric, $(0, 2)$ tensor field with an index of 1, it is referred to as a Lorentzian manifold. Dutch physicist Hendrik Lorentz introduced this concept, which was independently explored by Rosca and Mihai [16]. Since then, numerous geometers have been used to investigate Lorentzian manifolds [26], uncovering several important properties. Our current study focuses on a specific type of manifold known as Lorentzian β -Kenmotsu manifold ($\mathcal{M}_\beta$). First, we present an overview of the development of this manifold.

Within the field of differential geometry, the $\mathbb{M}$ -projective curvature tensor stands as a significant tensor, comparable in importance to the conformal curvature tensor. This particular tensor acts as a bridge, connecting the $\mathcal{H}$ -projective curvature tensor with three other tensors: the conharmonic, conformal, and concircular curvature tensors.

Definition 1.1 Consider $(\mathcal{M}^n, g)$, a smooth manifold of dimension n with $\mathbb{C}^\infty$ classification, endowed with a metric tensor g and a Riemannian connection ∇ . In 1971, Pokhariyal and Mishra [21] proposed the $\mathbb{M}$ -projective curvature tensor for the Riemannian manifold $(\mathcal{M}^n, g)$, which is expressed as follows:

$$\mathbb{M}(\mathcal{B}_1, \mathcal{B}_2)\mathcal{B}_3 = R(\mathcal{B}_1, \mathcal{B}_2)\mathcal{B}_3 - \frac{1}{2(n-1)}[S(\mathcal{B}_2, \mathcal{B}_3)\mathcal{B}_1 - S(\mathcal{B}_1, \mathcal{B}_3)\mathcal{B}_2 + g(\mathcal{B}_2, \mathcal{B}_3)Q\mathcal{B}_1 - g(\mathcal{B}_1, \mathcal{B}_3)Q\mathcal{B}_2], \quad (1.1)$$

for all smooth vector fields $\mathcal{B}_1, \mathcal{B}_2, \mathcal{B}_3 \in \chi(\mathcal{M}^n)$, here R is the curvature tensor, S is the Ricci tensor and Q is the Ricci operator defined by $S(\mathcal{B}_1, \mathcal{B}_2) = g(Q\mathcal{B}_1, \mathcal{B}_2)$.

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In 1981, Jean-Pierre Bourguignon [3] proposed the Ricci-Bourguignon (RB) flow, building upon unpublished insights from Lichnerowicz and a paper by Aubin [1]. The RB flow can be formally defined as [10]

Definition 1.2 On a Riemannian manifold $(\mathcal{M}^n, g)$ of dimension n , a set of metrics $g(t)$ is considered to develop according to the RB flow if $g(t)$ conforms to the following developmental equation:

$$\frac{\partial}{\partial t} g = -2(S - \psi r)g, \quad (1.2)$$

where S represents the Ricci tensor of type $(0, 2)$, r denotes the scalar curvature, and $\psi \in \mathbb{R}$ is a constant.

The previous definition shows that when $\psi = 0$ in (1.2), the flow transforms into Ricci flow. According to [10], various tensors emerge for different values of ψ : the Einstein tensor at $\psi = \frac{1}{2}$, the traceless Ricci tensor at $\psi = \frac{1}{n}$, the Schouten tensor at $\psi = \frac{1}{2(n-1)}$, and the Ricci tensor at $\psi = 0$.

In recent studies, Ho [12] explored this flow on locally homogeneous 3-manifolds. Additional research on this subject has been conducted in relation to the product of an Anti de Sitter space with a sphere [2]. Shubham Dwivedi [10] introduced a new extended form of soliton, termed the Ricci-Bourguignon soliton (RBS for short), which functions as interpolating soliton connecting Ricci and Yamabe solitons. Moreover, numerous researchers, including Dey [9] and Dey et al. [8], have investigated the Ricci-Bourguignon soliton.

Definition 1.3 A Riemannian manifold $(\mathcal{M}^n, g)$ is considered a RB soliton when there exists a vector field $\mathcal{B}_2$ on $\mathcal{M}$ that fulfills the following equation:

$$\mathcal{L}_{\mathcal{B}_2} g + 2S = 2\Lambda g + 2\psi r g, \quad (1.3)$$

where $\mathcal{L}_{\mathcal{B}_2} g$ represents the Lie derivative along the vector field $\mathcal{B}_2$, and $\Lambda \in \mathbb{R}$ is a real constant.

The classification of the system depends on the value of Λ : it is considered shrinking when $\Lambda > 0$, steady when $\Lambda = 0$, and expanding when $\Lambda < 0$. In cases where $\mathcal{B}_2 = \nabla f$, with f being a smooth function from $\mathcal{M}$ to $\mathbb{R}$, the system $(\mathcal{M}, g)$ is referred to as a gradient RBS (GRBS for short). Furthermore, if Λ in (1.3) is a smooth function from $\mathcal{M}$ to $\mathbb{R}$, then $(\mathcal{M}, g)$ is termed an almost RBS (ARBS for short). An ARBS becomes a gradient almost RBS (GARBS for short) when $\mathcal{B}_2 = \nabla f$ for a smooth function f on $\mathcal{M}$. The GARBS is categorized as shrinking, steady, or expanding based on whether $\Lambda > 0$, $\Lambda = 0$, or $\Lambda < 0$, respectively. It's worth noting that if $\mathcal{B}_2$ is a Killing vector field, an ARBS reduces to a RBS, as this condition necessitates Λ to be constant.

In [21], the authors explored the relativistic implications of the $\mathbb{M}$ -projective curvature tensor. Several authors have explored the $\mathbb{M}$ -projective curvature tensor, with notable contributions from Chaubey and Ojha [4], De and Mallick [5], as well as Singh [29]. In recent studies, the authors (see, [17], [24], [19], [18], [25], [30], [32], [33], [20]) have conducted comprehensive investigations into the characteristics of the $\mathbb{M}$ -projective curvature tensor across various types of manifolds. Motivated from all these studies, we explore some distinctive attributes of $\mathbb{M}$ -projective curvature tensor in $\mathcal{M}_\beta$.

The layout of the article is as follows: Section 2 provides a concise introduction to the $\mathcal{M}_\beta$. In section 3, we show that an $\mathbb{M}$ -projectively φ -recurrent $\mathcal{M}_\beta$ with invariant scalar curvature r is equivalent to an $\mathbb{M}$ -projectively φ -symmetric manifold. The $\mathbb{M}$ -projectively pseudo-symmetric $\mathcal{M}_\beta$ is examined in section 4. Section 5 explores the $\varphi - \mathbb{M}$ -projectively flat $\mathcal{M}_\beta$. Subsequently, section 6 analyzes the $\mathcal{M}_\beta$ that satisfies the $\mathbb{M}$ -projectively Ricci pseudo-symmetric condition. Section 7 investigates the $\mathcal{M}_\beta$ that fulfills the $R(\zeta, \mathcal{B}_3) \cdot \mathbb{M} = 0$ condition. The focus of section 8 is the cyclic parallel Ricci tensor. The next two sections examine the $\mathcal{V}^\flat$ -parallel Ricci tensor and Ricci-Bourguignon soliton. To validate our findings, the concluding portion showcases an illustration of a five-dimensional $\mathcal{M}_\beta$.

2 Preliminaries

A smooth manifold of dimension $(2n + 1)$ is characterized as Lorentzian β -Kenmotsu manifold $(\mathcal{M}_\beta)$ if it possesses a $(1, 1)$ -tensor field φ , a contravariant vector field ζ , a covariant vector field $\mathcal{V}^\flat$ and a Lorentzian metric g which satisfies

$$\varphi^2 \mathcal{B}_1 = \mathcal{B}_1 + \mathcal{V}^\flat(\mathcal{B}_1)\zeta, \quad g(\mathcal{B}_1, \zeta) = \mathcal{V}^\flat(\mathcal{B}_1), \quad (2.1)$$

$$\mathcal{V}^\flat(\zeta) = -1, \quad \varphi \zeta = 0, \quad \mathcal{V}^\flat(\varphi \mathcal{B}_1) = 0, \quad (2.2)$$

$$g(\varphi \mathcal{B}_1, \varphi \mathcal{B}_2) = g(\mathcal{B}_1, \mathcal{B}_2) + \mathcal{V}^\flat(\mathcal{B}_1)\mathcal{V}^\flat(\mathcal{B}_2), \quad (2.3)$$

$$g(\varphi \mathcal{B}_1, \mathcal{B}_2) = g(\mathcal{B}_1, \varphi \mathcal{B}_2), \quad (2.4)$$

for all $\mathcal{B}_1, \mathcal{B}_2 \in \chi(\mathcal{M}_\beta)$.

A $\mathcal{M}_\beta$ also fulfills

$$\nabla_{\mathcal{B}_1} \zeta = \beta[\mathcal{B}_1 - \mathcal{V}^\flat(\mathcal{B}_1)\zeta], \quad (2.5)$$

$$(\nabla_{\mathcal{B}_1} \mathcal{V}^\flat)(\mathcal{B}_2) = \beta[g(\mathcal{B}_1, \mathcal{B}_2) - \mathcal{V}^\flat(\mathcal{B}_1)\mathcal{V}^\flat(\mathcal{B}_2)], \quad (2.6)$$

where ∇ represents the covariant differentiation operator.

Moreover, on an $\mathcal{M}_\beta$, the following relations hold [23]:

$$\mathcal{V}^\flat(R(\mathcal{B}_1, \mathcal{B}_2)\mathcal{B}_3) = \beta^2[g(\mathcal{B}_1, \mathcal{B}_3)\mathcal{V}^\flat(\mathcal{B}_2) - g(\mathcal{B}_2, \mathcal{B}_3)\mathcal{V}^\flat(\mathcal{B}_1)], \quad (2.7)$$

$$R(\zeta, \mathcal{B}_1)\mathcal{B}_2 = \beta^2(\mathcal{V}^\flat(\mathcal{B}_2)\mathcal{B}_1 - g(\mathcal{B}_1, \mathcal{B}_2)\zeta), \quad (2.8)$$

$$R(\mathcal{B}_1, \mathcal{B}_2)\zeta = \beta^2(\mathcal{V}^\flat(\mathcal{B}_1)\mathcal{B}_2 - \mathcal{V}^\flat(\mathcal{B}_2)\mathcal{B}_1), \quad (2.9)$$

$$S(\mathcal{B}_1, \zeta) = -(n-1)\beta^2\mathcal{V}^\flat(\mathcal{B}_1), \quad (2.10)$$

$$Q\zeta = -(n-1)\beta^2\zeta, \quad (2.11)$$

$$S(\zeta, \zeta) = (n-1)\beta^2, \quad (2.12)$$

for any $\mathcal{B}_1, \mathcal{B}_2, \mathcal{B}_3 \in \chi(\mathcal{M}_\beta)$, where R and S denote the curvature tensor and Ricci tensor on $\mathcal{M}_\beta$ respectively.

Definition 2.1 An $\mathcal{M}_\beta$ is named a generalized $\mathcal{V}^\flat$ -Einstein manifold if [31]

$$S(\mathcal{B}_1, \mathcal{B}_2) = \gamma_1 g(\mathcal{B}_1, \mathcal{B}_2) + \gamma_2 \mathcal{V}^\flat(\mathcal{B}_1)\mathcal{V}^\flat(\mathcal{B}_2) + \gamma_3 \Phi(\mathcal{B}_1, \mathcal{B}_2), \quad (2.13)$$

here S represents the Ricci tensor of type $(0, 2)$; $\gamma_1, \gamma_2, \gamma_3$ are smooth functions and $\Phi(\mathcal{B}_1, \mathcal{B}_2) = g(\varphi \mathcal{B}_1, \mathcal{B}_2)$, is the fundamental 2-form of $\mathcal{M}_\beta$. If $\gamma_3 = 0$ (resp., $\gamma_2 = \gamma_3 = 0$), then an $\mathcal{M}_\beta$ reduces to a $\mathcal{V}^\flat$ -Einstein (resp., Einstein) manifold.

In particular, if $\gamma_3 = 0$, equation (2.13) reduces to

$$S(\mathcal{B}_1, \mathcal{B}_2) = \gamma_1 g(\mathcal{B}_1, \mathcal{B}_2) + \gamma_2 \mathcal{V}^\flat(\mathcal{B}_1)\mathcal{V}^\flat(\mathcal{B}_2). \quad (2.14)$$

In view of (2.1) and (2.14), we infer

$$Q\mathcal{B}_1 = \gamma_1 \mathcal{B}_1 + \gamma_2 \mathcal{V}^\flat(\mathcal{B}_1)\zeta. \quad (2.15)$$

Substituting $\mathcal{B}_1 = \mathcal{B}_2 = e_i$ in (2.14), and summing for $1 \leq i \leq n$, we achieve

$$r = n\gamma_1 - \gamma_2. \quad (2.16)$$

Now, putting $\mathcal{B}_1 = \mathcal{B}_2 = \zeta$ in (2.14) and using (2.1), (2.2) and (2.12), we obtain

$$\gamma_2 - \gamma_1 = (n-1)\beta^2. \quad (2.17)$$

From the condition (2.16) and (2.17), we have

$$\gamma_1 = \frac{r}{(n-1)} + \beta^2 \quad \text{and} \quad \gamma_2 = \frac{r}{(n-1)} + n\beta^2, \quad (2.18)$$

where r is the scalar curvature.

Thus, (2.14) and (2.18) together gives

$$S(\mathcal{B}_1, \mathcal{B}_2) = \left[\frac{r}{(n-1)} + \beta^2 \right] g(\mathcal{B}_1, \mathcal{B}_2) + \left[\frac{r}{(n-1)} + n\beta^2 \right] \mathcal{V}^\flat(\mathcal{B}_1)\mathcal{V}^\flat(\mathcal{B}_2). \quad (2.19)$$

3 $\mathbb{M}$ -Projectively φ -recurrent $\mathcal{M}_\beta$

Definition 3.1 An $\mathcal{M}_\beta$ is considered $\mathbb{M}$ -projectively φ -recurrent if for any non-zero one form $\mathcal{A}$, it fulfills the following condition [28]:

$$\varphi^2((\nabla_{\mathcal{B}_4} \mathbb{M})(\mathcal{B}_1, \mathcal{B}_2)\mathcal{B}_3) = \mathcal{A}(\mathcal{B}_4)\mathbb{M}(\mathcal{B}_1, \mathcal{B}_2)\mathcal{B}_3, \quad (3.1)$$

where $\mathcal{B}_1, \mathcal{B}_2, \mathcal{B}_3, \mathcal{B}_4 \in \chi(\mathcal{M}_\beta)$.

In view of (2.1) in (3.1),

$$(\nabla_{\mathcal{B}_4}\mathbb{M})(\mathcal{B}_1, \mathcal{B}_2)\mathcal{B}_3 + \mathcal{V}^b((\nabla_{\mathcal{B}_4}\mathbb{M})(\mathcal{B}_1, \mathcal{B}_2)\mathcal{B}_3)\zeta = \mathcal{A}(\mathcal{B}_4)\mathbb{M}(\mathcal{B}_1, \mathcal{B}_2)\mathcal{B}_3, \quad (3.2)$$

which yields

$$g((\nabla_{\mathcal{B}_4}\mathbb{M})(\mathcal{B}_1, \mathcal{B}_2)\mathcal{B}_3, \mathcal{Z}) + \mathcal{V}^b((\nabla_{\mathcal{B}_4}\mathbb{M})(\mathcal{B}_1, \mathcal{B}_2)\mathcal{B}_3)\mathcal{V}^b(\mathcal{Z}) = \mathcal{A}(\mathcal{B}_4)g(\mathbb{M}(\mathcal{B}_1, \mathcal{B}_2)\mathcal{B}_3, \mathcal{Z}). \quad (3.3)$$

Incorporating equation (1.1) into the aforementioned expression and subsequently performing contraction with respect to $\mathcal{B}_1$ and $\mathcal{Z}$ yields

$$\begin{aligned} (n+1)(\nabla_{\mathcal{B}_4}S)(\mathcal{B}_2, \mathcal{B}_3) - g(\mathcal{B}_2, \mathcal{B}_3)dr(\mathcal{B}_4) + 2(n-1)\mathcal{V}^b((\nabla_{\mathcal{B}_4}R)(\zeta, \mathcal{B}_2)\mathcal{B}_3) + \mathcal{V}^b(\mathcal{B}_2)(\nabla_{\mathcal{B}_4}S)(\zeta, \mathcal{B}_3) \\ - g(\mathcal{B}_2, \mathcal{B}_3)(\nabla_{\mathcal{B}_4}S)(\zeta, \zeta) + \mathcal{V}^b(\mathcal{B}_3)(\nabla_{\mathcal{B}_4}S)(\mathcal{B}_2, \zeta) = \mathcal{A}(\mathcal{B}_4)[nS(\mathcal{B}_2, \mathcal{B}_3) - rg(\mathcal{B}_2, \mathcal{B}_3)]. \end{aligned} \quad (3.4)$$

In light of the equations (2.10), (2.12), (2.5) and (2.6) in (3.4), we achieve

$$\begin{aligned} (n+1)(\nabla_{\mathcal{B}_4}S)(\mathcal{B}_2, \mathcal{B}_3) - g(\mathcal{B}_2, \mathcal{B}_3)dr(\mathcal{B}_4) + 2(n-1)\beta^3[g(\mathcal{B}_4, \mathcal{B}_3)\mathcal{V}^b(\mathcal{B}_2) - \mathcal{V}^b(\mathcal{B}_4)\mathcal{V}^b(\mathcal{B}_3)\mathcal{V}^b(\mathcal{B}_2) \\ - 4g(\mathcal{B}_2, \mathcal{B}_3)\mathcal{V}^b(\mathcal{B}_4)] + \beta\left\{(n-1)\beta^2\mathcal{V}^b(\nabla_{\mathcal{B}_4}\mathcal{B}_3) - S(\mathcal{B}_4, \mathcal{B}_3)\right\}\mathcal{V}^b(\mathcal{B}_2) \\ + \beta\left\{(n-1)\beta^2\mathcal{V}^b(\nabla_{\mathcal{B}_4}\mathcal{B}_2) - S(\mathcal{B}_4, \mathcal{B}_2)\right\}\mathcal{V}^b(\mathcal{B}_3) = \mathcal{A}(\mathcal{B}_4)[nS(\mathcal{B}_2, \mathcal{B}_3) - rg(\mathcal{B}_2, \mathcal{B}_3)]. \end{aligned} \quad (3.5)$$

Putting $\mathcal{B}_2 = \mathcal{B}_3 = \zeta$ in (3.5) and using (2.1), we obtain

$$\mathcal{A}(\mathcal{B}_4) = \frac{dr(\mathcal{B}_4) + 2(n-1)(2n+1)\beta^3\mathcal{V}^b(\mathcal{B}_4)}{r + n(n-1)\beta^2}. \quad (3.6)$$

Thus, we arrive at the following conclusion:

Theorem 3.1 In an n -dimensional $\mathbb{M}$ -projectively φ -recurrent $\mathcal{M}_\beta$, the non-zero 1-form $\mathcal{A}$ is given by (3.6), provided that $r \neq -n(n-1)\beta^2$.

Additionally, assuming the scalar curvature of an $\mathbb{M}$ -projectively φ -recurrent $\mathcal{M}_\beta$ remains constant, we can conclude that $dr(\mathcal{B}_4) = 0$. Consequently, the equation (3.6) leads to

$$\mathcal{A}(\mathcal{B}_4) = \frac{2(n-1)(2n+1)\beta^3}{r + n(n-1)\beta^2}\mathcal{V}^b(\mathcal{B}_4). \quad (3.7)$$

Making use of (3.7) in (3.1), we obtain

$$\varphi^2((\nabla_{\mathcal{B}_4}\mathbb{M})(\mathcal{B}_1, \mathcal{B}_2)\mathcal{B}_3) \neq 0. \quad (3.8)$$

Hence, we can state the following result.

Theorem 3.2 The $\mathbb{M}$ -projectively φ -recurrent $\mathcal{M}_\beta$ possessing a constant scalar curvature r never reduces to an $\mathbb{M}$ -projectively φ -symmetric manifold [28].

4 $\mathbb{M}$ -Projectively Pseudo-symmetric $\mathcal{M}_\beta$

Definition 4.1 An $\mathcal{M}_\beta$ is termed as $\mathbb{M}$ -projectively pseudo-symmetric if its curvature tensor satisfies [28]

$$(R(\mathcal{B}_1, \mathcal{B}_2) \cdot \mathbb{M})(\mathcal{B}_3, \mathcal{Z})\mathcal{B}_4 = \mathcal{L}_\mathbb{M}[(\mathcal{B}_1 \wedge \mathcal{B}_2) \cdot \mathbb{M})(\mathcal{B}_3, \mathcal{Z})\mathcal{B}_4], \quad (4.1)$$

on $\mathcal{B}_{1\mathbb{M}} = \{x \in \mathcal{M}_\beta : \mathbb{M} \neq 0 \text{ at } x\}$, where $\mathcal{L}_\mathbb{M}$ is any function on $\mathcal{B}_{1\mathbb{M}}$.

In view of equation (4.1), we can express it as follows:

$$\begin{aligned} (R(\mathcal{B}_1, \zeta) \cdot \mathbb{M})(\mathcal{B}_3, \mathcal{Z})\mathcal{B}_4 = \mathcal{L}_\mathbb{M}[(\mathcal{B}_1 \wedge \zeta)(\mathbb{M}(\mathcal{B}_3, \mathcal{Z})\mathcal{B}_4)) - \mathbb{M}((\mathcal{B}_1 \wedge \zeta)\mathcal{B}_3, \mathcal{Z})\mathcal{B}_4 \\ - \mathbb{M}(\mathcal{B}_3, (\mathcal{B}_1 \wedge \zeta)\mathcal{Z})\mathcal{B}_4 - \mathbb{M}(\mathcal{B}_3, \mathcal{Z})(\mathcal{B}_1 \wedge \zeta)\mathcal{B}_4]. \end{aligned} \quad (4.2)$$

From the left-hand side of (4.2), we can readily obtain

$$\beta^2[\mathcal{V}^b(\mathbb{M}(\mathcal{B}_3, \mathcal{Z})\mathcal{B}_4)\mathcal{B}_1 - g(\mathcal{B}_1, \mathbb{M}(\mathcal{B}_3, \mathcal{Z})\mathcal{B}_4)\zeta - \mathcal{V}^b(\mathcal{B}_3)\mathbb{M}(\mathcal{B}_1, \mathcal{Z})\mathcal{B}_4 + g(\mathcal{B}_1, \mathcal{B}_3)\mathbb{M}(\zeta, \mathcal{Z})\mathcal{B}_4 - \mathcal{V}^b(\mathcal{Z})\mathbb{M}(\mathcal{B}_3, \mathcal{B}_1)\mathcal{B}_4 + g(\mathcal{B}_1, \mathcal{Z})\mathbb{M}(\mathcal{B}_3, \zeta)\mathcal{B}_4 - \mathcal{V}^b(\mathcal{B}_4)\mathbb{M}(\mathcal{B}_3, \mathcal{Z})\mathcal{B}_1 + g(\mathcal{B}_1, \mathcal{B}_4)\mathbb{M}(\mathcal{B}_3, \mathcal{Z})\zeta]. \quad (4.3)$$

In a similar manner, the right-hand side of (4.2) produces

$$\mathcal{L}_{\mathbb{M}}[\mathcal{V}^b(\mathbb{M}(\mathcal{B}_3, \mathcal{Z})\mathcal{B}_4)\mathcal{B}_1 - g(\mathcal{B}_1, \mathbb{M}(\mathcal{B}_3, \mathcal{Z})\mathcal{B}_4)\zeta - \mathcal{V}^b(\mathcal{B}_3)\mathbb{M}(\mathcal{B}_1, \mathcal{Z})\mathcal{B}_4 + g(\mathcal{B}_1, \mathcal{B}_3)\mathbb{M}(\zeta, \mathcal{Z})\mathcal{B}_4 - \mathcal{V}^b(\mathcal{Z})\mathbb{M}(\mathcal{B}_3, \mathcal{B}_1)\mathcal{B}_4 + g(\mathcal{B}_1, \mathcal{Z})\mathbb{M}(\mathcal{B}_3, \zeta)\mathcal{B}_4 - \mathcal{V}^b(\mathcal{B}_4)\mathbb{M}(\mathcal{B}_3, \mathcal{Z})\mathcal{B}_1 + g(\mathcal{B}_1, \mathcal{B}_4)\mathbb{M}(\mathcal{B}_3, \mathcal{Z})\zeta]. \quad (4.4)$$

Now, the preceding equation (4.2) can take the form

$$(\mathcal{L}_{\mathbb{M}} - \beta^2)[\mathcal{V}^b(\mathbb{M}(\mathcal{B}_3, \mathcal{Z})\mathcal{B}_4)\mathcal{B}_1 - g(\mathcal{B}_1, \mathbb{M}(\mathcal{B}_3, \mathcal{Z})\mathcal{B}_4)\zeta - \mathcal{V}^b(\mathcal{B}_3)\mathbb{M}(\mathcal{B}_1, \mathcal{Z})\mathcal{B}_4 + g(\mathcal{B}_1, \mathcal{B}_3)\mathbb{M}(\zeta, \mathcal{Z})\mathcal{B}_4 - \mathcal{V}^b(\mathcal{Z})\mathbb{M}(\mathcal{B}_3, \mathcal{B}_1)\mathcal{B}_4 + g(\mathcal{B}_1, \mathcal{Z})\mathbb{M}(\mathcal{B}_3, \zeta)\mathcal{B}_4 - \mathcal{V}^b(\mathcal{B}_4)\mathbb{M}(\mathcal{B}_3, \mathcal{Z})\mathcal{B}_1 + g(\mathcal{B}_1, \mathcal{B}_4)\mathbb{M}(\mathcal{B}_3, \mathcal{Z})\zeta] = 0. \quad (4.5)$$

Substituting $\mathcal{Z} = \zeta$ into equation (4.5) and utilizing equation (1.1), we find that either $\mathcal{L}_{\mathbb{M}} = \beta^2$ or

$$\mathbb{M}(\mathcal{B}_3, \mathcal{B}_1)\mathcal{B}_4 = -\mathcal{V}^b(\mathbb{M}(\mathcal{B}_3, \zeta)\mathcal{B}_4)\mathcal{B}_1 + g(\mathcal{B}_1, \mathbb{M}(\mathcal{B}_3, \zeta)\mathcal{B}_4)\zeta + \mathcal{V}^b(\mathcal{B}_3)\mathbb{M}(\mathcal{B}_1, \zeta)\mathcal{B}_4 - \mathcal{V}^b(\mathcal{B}_1)\mathbb{M}(\mathcal{B}_3, \zeta)\mathcal{B}_4 + \mathcal{V}^b(\mathcal{B}_4)\mathbb{M}(\mathcal{B}_3, \zeta)\mathcal{B}_1 - g(\mathcal{B}_1, \mathcal{B}_4)\mathbb{M}(\mathcal{B}_3, \zeta)\zeta. \quad (4.6)$$

By utilizing equations (1.1), (2.2), (2.3), (2.7), and (2.10), equation (4.6) can be rewritten as

$$\mathbb{M}(\mathcal{B}_3, \mathcal{B}_1)\mathcal{B}_4 = \frac{\beta^2}{2} \left[g(\mathcal{B}_3, \mathcal{B}_4)\mathcal{B}_1 + \mathcal{V}^b(\mathcal{B}_3)g(\mathcal{B}_1, \mathcal{B}_4)\zeta + \mathcal{V}^b(\mathcal{B}_4)g(\mathcal{B}_3, \mathcal{B}_1)\zeta \right] + \frac{1}{2(n-1)} \left[S(\mathcal{B}_3, \mathcal{B}_4)\mathcal{B}_1 + \mathcal{V}^b(\mathcal{B}_3)S(\mathcal{B}_1, \mathcal{B}_4)\zeta + \mathcal{V}^b(\mathcal{B}_4)S(\mathcal{B}_3, \mathcal{B}_1)\zeta \right]. \quad (4.7)$$

Contracting (4.7) with respect to $\mathcal{B}_3$ yields

$$S(\mathcal{B}_1, \mathcal{B}_4) = - \left[\frac{3(n^2 - 1)\beta^2 + r}{(2n - 3)} \right] g(\mathcal{B}_1, \mathcal{B}_4). \quad (4.8)$$

Upon contracting (4.8) once more, we infer

$$r = -n(n+1)\beta^2. \quad (4.9)$$

Hence, we state an important observation:

Theorem 4.1 *In an n -dimensional $\mathbb{M}$ -projectively pseudo-symmetric $\mathcal{M}_\beta$, either $\mathcal{L}_{\mathbb{M}} = \beta^2$ or the manifold reduces to an Einstein manifold having constant scalar curvature $-n(n+1)\beta^2$.*

5 $\phi - \mathbb{M}$ -Projectively flat $\mathcal{M}_\beta$

Definition 5.1 *An $\mathcal{M}_\beta$ is said to be $\phi - \mathbb{M}$ -projectively flat if [25]*

$$\phi^2(\mathbb{M}(\phi\mathcal{B}_1, \phi\mathcal{B}_2)\phi\mathcal{B}_3) = 0, \quad (5.1)$$

for all $\mathcal{B}_1, \mathcal{B}_2, \mathcal{B}_3 \in \chi(\mathcal{M}_\beta)$.

It's apparent that $\phi^2(\mathbb{M}(\phi\mathcal{B}_1, \phi\mathcal{B}_2)\phi\mathcal{B}_3) = 0$ holds if

$$g(\mathbb{M}(\phi\mathcal{B}_1, \phi\mathcal{B}_2)\phi\mathcal{B}_3, \phi\mathcal{B}_4) = 0, \quad (5.2)$$

for all $\mathcal{B}_1, \mathcal{B}_2, \mathcal{B}_3, \mathcal{B}_4 \in \chi(\mathcal{M}_\beta)$.

Making use of (1.1), we have

$$g(R(\phi\mathcal{B}_1, \phi\mathcal{B}_2)\phi\mathcal{B}_3, \phi\mathcal{B}_4) = \frac{1}{2(n-1)} [S(\phi\mathcal{B}_2, \phi\mathcal{B}_3)g(\phi\mathcal{B}_1, \phi\mathcal{B}_4) - S(\phi\mathcal{B}_1, \phi\mathcal{B}_3)g(\phi\mathcal{B}_2, \phi\mathcal{B}_4) + g(\phi\mathcal{B}_2, \phi\mathcal{B}_3)S(\phi\mathcal{B}_1, \phi\mathcal{B}_4) - g(\phi\mathcal{B}_1, \phi\mathcal{B}_3)S(\phi\mathcal{B}_2, \phi\mathcal{B}_4)]. \quad (5.3)$$

Consider a local orthonormal basis of vector fields on $\mathcal{M}_\beta$, represented as $\{\varphi e_1, \varphi e_2, \dots, \varphi e_{n-1}, \zeta\}$ at any given point. By setting $\mathcal{B}_1 = \mathcal{B}_4 = e_i$ in (5.3) and summing over i , where $1 \leq i \leq (n-1)$, we obtain

$$\sum_{i=1}^{n-1} g(R(\varphi e_i, \varphi \mathcal{B}_2) \varphi \mathcal{B}_3, \varphi e_i) = \frac{1}{2(n-1)} \sum_{i=1}^{n-1} [S(\varphi \mathcal{B}_2, \varphi \mathcal{B}_3) g(\varphi e_i, \varphi e_i) - S(\varphi e_i, \varphi \mathcal{B}_3) g(\varphi \mathcal{B}_2, \varphi e_i) + g(\varphi \mathcal{B}_2, \varphi \mathcal{B}_3) S(\varphi e_i, \varphi e_i) - g(\varphi e_i, \varphi \mathcal{B}_3) S(\varphi \mathcal{B}_2, \varphi e_i)], \quad (5.4)$$

which reduces to

$$S(\varphi \mathcal{B}_2, \varphi \mathcal{B}_3) = \frac{r}{(n+1)} g(\varphi \mathcal{B}_2, \varphi \mathcal{B}_3). \quad (5.5)$$

In the view of (2.3) in (5.5), we have

$$S(\mathcal{B}_2, \mathcal{B}_3) = \frac{r}{(n+1)} g(\mathcal{B}_2, \mathcal{B}_3) + \frac{[r + (n^2 - 1)\beta^2]}{(n+1)} \mathcal{V}^\flat(\mathcal{B}_2) \mathcal{V}^\flat(\mathcal{B}_3). \quad (5.6)$$

Taking frame field over $\mathcal{B}_2$ and $\mathcal{B}_3$, we acquire

$$r = -\frac{(n^2 - 1)}{2} \beta^2. \quad (5.7)$$

As a result, we reach the following determination:

Theorem 5.1 An n -dimensional $\varphi - \mathbb{M}$ -projectively flat $\mathcal{M}_\beta$ is $\mathcal{V}^\flat$ -Einstein manifold with constant scalar curvature $-\frac{(n^2 - 1)}{2} \beta^2$.

6 $\mathcal{M}_\beta$ Satisfying $\mathbb{M}$ -Projectively Ricci Pseudo-symmetric Condition

Deszcz proposed the concept of *Ricci pseudo symmetric* manifold ([6], [7]). A geometric interpretation for these manifolds, specifically in the Riemannian case, is presented in [14].

Definition 6.1 A Riemannian manifold $(\mathcal{M}^n, g)$ is termed as *Ricci pseudo-symmetric* ([6],[7],[13],[27]) if the Tachibana tensor $\tilde{Q}(g, S)$ and the tensor $R \cdot S$ are linearly dependent, where

$$(R(\mathcal{B}_1, \mathcal{B}_2) \cdot S)(\mathcal{B}_3, \mathcal{B}_4) = -S(R(\mathcal{B}_1, \mathcal{B}_2) \mathcal{B}_3, \mathcal{B}_4) - S(\mathcal{B}_3, R(\mathcal{B}_1, \mathcal{B}_2) \mathcal{B}_4), \quad (6.1)$$

$$\mathcal{F}_S \tilde{Q}(g, S)(\mathcal{B}_3, \mathcal{B}_4; \mathcal{B}_1, \mathcal{B}_2) = -S((\mathcal{B}_1 \wedge_g \mathcal{B}_2) \mathcal{B}_3, \mathcal{B}_4) - S(\mathcal{B}_3, (\mathcal{B}_1 \wedge_g \mathcal{B}_2) \mathcal{B}_4), \quad (6.2)$$

and

$$(\mathcal{B}_1 \wedge_g \mathcal{B}_2) \mathcal{B}_3 = g(\mathcal{B}_2, \mathcal{B}_3) \mathcal{B}_1 - g(\mathcal{B}_1, \mathcal{B}_3) \mathcal{B}_2, \quad (6.3)$$

holds for $\mathcal{B}_1, \mathcal{B}_2, \mathcal{B}_3, \mathcal{B}_4 \in \chi(\mathcal{M}^n)$, and R denotes the curvature tensor of $\mathcal{M}^n$.

Definition 6.2 An $\mathcal{M}_\beta$ is termed as $\mathbb{M}$ -projectively Ricci pseudo-symmetric if it's curvature tensor satisfies [22]

$$(\mathbb{M}(\mathcal{B}_1, \mathcal{B}_2) \cdot S)(\mathcal{B}_3, \mathcal{B}_4) = \mathcal{F}_S \tilde{Q}(g, S)(\mathcal{B}_3, \mathcal{B}_4; \mathcal{B}_1, \mathcal{B}_2), \quad (6.4)$$

on $\mathcal{B}_{1S} = \{x \in \mathcal{M}_\beta : S \neq \frac{r}{n} g \text{ at } x\}$, where $\mathcal{F}_S$ is any function on $\mathcal{B}_{1S}$.

In view of (6.4), we have

$$S(\mathbb{M}(\mathcal{B}_1, \mathcal{B}_2) \mathcal{B}_3, \mathcal{B}_4) + S(\mathcal{B}_3, \mathbb{M}(\mathcal{B}_1, \mathcal{B}_2) \mathcal{B}_4) = \mathcal{F}_S [g(\mathcal{B}_2, \mathcal{B}_3) S(\mathcal{B}_1, \mathcal{B}_4) - g(\mathcal{B}_1, \mathcal{B}_3) S(\mathcal{B}_2, \mathcal{B}_4) + g(\mathcal{B}_2, \mathcal{B}_4) S(\mathcal{B}_1, \mathcal{B}_3) - g(\mathcal{B}_1, \mathcal{B}_4) S(\mathcal{B}_2, \mathcal{B}_3)]. \quad (6.5)$$

Plugging $\mathcal{B}_3 = \zeta$ in (6.5), we have

$$S(\mathbb{M}(\mathcal{B}_1, \mathcal{B}_2) \zeta, \mathcal{B}_4) + S(\zeta, \mathbb{M}(\mathcal{B}_1, \mathcal{B}_2) \mathcal{B}_4) = \mathcal{F}_S [g(\mathcal{B}_2, \zeta) S(\mathcal{B}_1, \mathcal{B}_4) - g(\mathcal{B}_1, \zeta) S(\mathcal{B}_2, \mathcal{B}_4) + g(\mathcal{B}_2, \mathcal{B}_4) S(\mathcal{B}_1, \zeta) - g(\mathcal{B}_1, \mathcal{B}_4) S(\mathcal{B}_2, \zeta)]. \quad (6.6)$$

By using (2.10) and (1.1) in (6.6) and on simplification, we obtain

$$\begin{aligned} & \beta^2 \left\{ \mathcal{V}^b(\mathcal{B}_1)S(\mathcal{B}_2, \mathcal{B}_4) - \mathcal{V}^b(\mathcal{B}_2)S(\mathcal{B}_1, \mathcal{B}_4) \right\} - (n-1)\beta^2 \left\{ g(\mathcal{B}_1, \mathcal{B}_4)\mathcal{V}^b(\mathcal{B}_2) - g(\mathcal{B}_2, \mathcal{B}_4)\mathcal{V}^b(\mathcal{B}_1) \right\} \\ & - \frac{\beta^2}{2} [2\mathcal{V}^b(\mathcal{B}_1)S(\mathcal{B}_2, \mathcal{B}_4) - 2\mathcal{V}^b(\mathcal{B}_2)S(\mathcal{B}_1, \mathcal{B}_4) - S(\mathcal{B}_2, \mathcal{B}_4)\mathcal{V}^b(\mathcal{B}_1) + S(\mathcal{B}_1, \mathcal{B}_4)\mathcal{V}^b(\mathcal{B}_2) \\ & + (n-1)\beta^2 \left\{ g(\mathcal{B}_2, \mathcal{B}_4)\mathcal{V}^b(\mathcal{B}_1) - g(\mathcal{B}_1, \mathcal{B}_4)\mathcal{V}^b(\mathcal{B}_2) \right\}] = \mathcal{F}_S[\mathcal{V}^b(\mathcal{B}_2)S(\mathcal{B}_1, \mathcal{B}_4) - \mathcal{V}^b(\mathcal{B}_1)S(\mathcal{B}_2, \mathcal{B}_4) \\ & - (n-1)\beta^2 \left\{ g(\mathcal{B}_2, \mathcal{B}_4)\mathcal{V}^b(\mathcal{B}_1) - g(\mathcal{B}_1, \mathcal{B}_4)\mathcal{V}^b(\mathcal{B}_2) \right\}]. \quad (6.7) \end{aligned}$$

Putting $\mathcal{B}_2 = \zeta$ in (6.7) and making use of (2.10) and (2.1), it yields

$$(2\mathcal{F}_S + \beta^2)S(\mathcal{B}_1, \mathcal{B}_4) + (n-1)\beta^4(2\mathcal{F}_S + 1)g(\mathcal{B}_1, \mathcal{B}_4) = 0, \quad (6.8)$$

$$\text{or, } S(\mathcal{B}_1, \mathcal{B}_4) = \frac{-(n-1)\beta^4(2\mathcal{F}_S + 1)}{(2\mathcal{F}_S + \beta^2)}g(\mathcal{B}_1, \mathcal{B}_4). \quad (6.9)$$

Taking frame field over $\mathcal{B}_1$ and $\mathcal{B}_4$, we infer

$$r = \frac{-n(n-1)\beta^4(2\mathcal{F}_S + 1)}{(2\mathcal{F}_S + \beta^2)}. \quad (6.10)$$

Therefore, we propose the following theorems.

Theorem 6.1 *If an $\mathcal{M}_\beta$ is satisfying $\mathbb{M}$ -projectively Ricci pseudo-symmetric condition then the manifold is an Einstein manifold having constant scalar curvature $\frac{-n(n-1)\beta^4(2\mathcal{F}_S + 1)}{(2\mathcal{F}_S + \beta^2)}$.*

7 $\mathcal{M}_\beta$ Satisfying $R(\zeta, \mathcal{B}_3) \cdot \mathbb{M} = 0$ Condition

In the present section, we study $\mathcal{M}_\beta$ fulfilling $R(\zeta, \mathcal{B}_3) \cdot \mathbb{M} = 0$. Then, we have

$$R(\zeta, \mathcal{B}_3)\mathbb{M}(\mathcal{B}_1, \mathcal{B}_2)\mathcal{B}_4 - \mathbb{M}(R(\zeta, \mathcal{B}_3)\mathcal{B}_1, \mathcal{B}_2)\mathcal{B}_4 - \mathbb{M}(\mathcal{B}_1, R(\zeta, \mathcal{B}_3)\mathcal{B}_2)\mathcal{B}_4 - \mathbb{M}(\mathcal{B}_1, \mathcal{B}_2)R(\zeta, \mathcal{B}_3)\mathcal{B}_4 = 0. \quad (7.1)$$

We fetch the equation (2.8) into (7.1) to achieve

$$\begin{aligned} & \mathcal{V}^b(\mathbb{M}(\mathcal{B}_1, \mathcal{B}_2)\mathcal{B}_4)\mathcal{B}_3 - g(\mathcal{B}_3, \mathbb{M}(\mathcal{B}_1, \mathcal{B}_2)\mathcal{B}_4)\zeta - \mathcal{V}^b(\mathcal{B}_1)\mathbb{M}(\mathcal{B}_3, \mathcal{B}_2)\mathcal{B}_4 + g(\mathcal{B}_3, \mathcal{B}_1)\mathbb{M}(\zeta, \mathcal{B}_2)\mathcal{B}_4 \\ & - \mathcal{V}^b(\mathcal{B}_2)\mathbb{M}(\mathcal{B}_1, \mathcal{B}_3)\mathcal{B}_4 + g(\mathcal{B}_3, \mathcal{B}_2)\mathbb{M}(\mathcal{B}_1, \zeta)\mathcal{B}_4 - \mathcal{V}^b(\mathcal{B}_4)\mathbb{M}(\mathcal{B}_1, \mathcal{B}_2)\mathcal{B}_3 + g(\mathcal{B}_3, \mathcal{B}_4)\mathbb{M}(\mathcal{B}_1, \mathcal{B}_2)\zeta = 0. \quad (7.2) \end{aligned}$$

By taking inner product with ζ in (7.2), we acquire

$$\begin{aligned} & \mathcal{V}^b(\mathbb{M}(\mathcal{B}_1, \mathcal{B}_2)\mathcal{B}_4)\mathcal{V}^b(\mathcal{B}_3) + g(\mathcal{B}_3, \mathbb{M}(\mathcal{B}_1, \mathcal{B}_2)\mathcal{B}_4) - \mathcal{V}^b(\mathcal{B}_1)\mathcal{V}^b(\mathbb{M}(\mathcal{B}_3, \mathcal{B}_2)\mathcal{B}_4) + g(\mathcal{B}_3, \mathcal{B}_1)\mathcal{V}^b(\mathbb{M}(\zeta, \mathcal{B}_2)\mathcal{B}_4) \\ & - \mathcal{V}^b(\mathcal{B}_2)\mathcal{V}^b(\mathbb{M}(\mathcal{B}_1, \mathcal{B}_3)\mathcal{B}_4) + g(\mathcal{B}_3, \mathcal{B}_2)\mathcal{V}^b(\mathbb{M}(\mathcal{B}_1, \zeta)\mathcal{B}_4) - \mathcal{V}^b(\mathcal{B}_4)\mathcal{V}^b(\mathbb{M}(\mathcal{B}_1, \mathcal{B}_2)\mathcal{B}_3) \\ & + g(\mathcal{B}_3, \mathcal{B}_4)\mathcal{V}^b(\mathbb{M}(\mathcal{B}_1, \mathcal{B}_2)\zeta) = 0. \quad (7.3) \end{aligned}$$

Utilizing equation (1.1) and simplifying, we arrive at

$$\begin{aligned} & g(\mathcal{B}_3, R(\mathcal{B}_1, \mathcal{B}_2)\mathcal{B}_4) + \frac{\beta^2}{2}[g(\mathcal{B}_3, \mathcal{B}_1)g(\mathcal{B}_2, \mathcal{B}_4) - g(\mathcal{B}_1, \mathcal{B}_4)g(\mathcal{B}_3, \mathcal{B}_2)] - \frac{1}{2(n-1)}[-S(\mathcal{B}_2, \mathcal{B}_4)g(\mathcal{B}_3, \mathcal{B}_1) \\ & + (n-1)\beta^2g(\mathcal{B}_3, \mathcal{B}_1)\mathcal{V}^b(\mathcal{B}_4)\mathcal{V}^b(\mathcal{B}_2) - (n-1)\beta^2g(\mathcal{B}_3, \mathcal{B}_2)\mathcal{V}^b(\mathcal{B}_4)\mathcal{V}^b(\mathcal{B}_1) + g(\mathcal{B}_3, \mathcal{B}_2)S(\mathcal{B}_1, \mathcal{B}_4) \\ & - S(\mathcal{B}_2, \mathcal{B}_3)\mathcal{V}^b(\mathcal{B}_1)\mathcal{V}^b(\mathcal{B}_4) + S(\mathcal{B}_1, \mathcal{B}_3)\mathcal{V}^b(\mathcal{B}_2)\mathcal{V}^b(\mathcal{B}_4)] = 0. \quad (7.4) \end{aligned}$$

Consider an orthonormal frame field $\{e_i\}_{i=1}^n$ defined at any point on $\mathcal{M}_\beta$. If we set $\mathcal{B}_1 = \mathcal{B}_3 = e_i$ in (7.4) and summing over i , $1 \leq i \leq n$, we have

$$S(\mathcal{B}_2, \mathcal{B}_4) = -\frac{(n-1)\beta^2}{3}g(\mathcal{B}_2, \mathcal{B}_4) + \frac{[n(n-1)\beta^2 + r]}{3(n-1)}\mathcal{V}^b(\mathcal{B}_2)\mathcal{V}^b(\mathcal{B}_4). \quad (7.5)$$

As a result, we reach at following determination:

Theorem 7.1 *If a $\mathcal{M}_\beta$ fulfills the condition $R(\zeta, \mathcal{B}_3) \cdot \mathbb{M} = 0$, then the manifold is an $\mathcal{V}^b$ -Einstein manifold.*

8 Cyclic Parallel Ricci Tensor

Assuming that $\mathcal{M}_\beta$ has a cyclic parallel Ricci tensor [11], the Ricci tensor S satisfies

$$(\nabla_{\mathcal{B}_1} S)(\mathcal{B}_2, \mathcal{B}_3) + (\nabla_{\mathcal{B}_2} S)(\mathcal{B}_3, \mathcal{B}_1) + (\nabla_{\mathcal{B}_3} S)(\mathcal{B}_1, \mathcal{B}_2) = 0. \quad (8.1)$$

By applying the covariant derivative to (2.19) w.r.t. any vector field $\mathcal{B}_1$ and utilizing (2.6), we obtain

$$\begin{aligned} (\nabla_{\mathcal{B}_1} S)(\mathcal{B}_2, \mathcal{B}_3) &= \frac{dr(\mathcal{B}_1)}{n-1} \left\{ g(\mathcal{B}_2, \mathcal{B}_3) + \mathcal{V}^\flat(\mathcal{B}_2) \mathcal{V}^\flat(\mathcal{B}_3) \right\} \\ &\quad + \beta \left(\frac{r}{n-1} + n\beta^2 \right) [g(\mathcal{B}_1, \mathcal{B}_2) \mathcal{V}^\flat(\mathcal{B}_3) + g(\mathcal{B}_1, \mathcal{B}_3) \mathcal{V}^\flat(\mathcal{B}_2) - 2\mathcal{V}^\flat(\mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_2) \mathcal{V}^\flat(\mathcal{B}_3)]. \end{aligned} \quad (8.2)$$

Likewise, we can find

$$\begin{aligned} (\nabla_{\mathcal{B}_2} S)(\mathcal{B}_3, \mathcal{B}_1) &= \frac{dr(\mathcal{B}_2)}{n-1} \left\{ g(\mathcal{B}_3, \mathcal{B}_1) + \mathcal{V}^\flat(\mathcal{B}_3) \mathcal{V}^\flat(\mathcal{B}_1) \right\} \\ &\quad + \beta \left(\frac{r}{n-1} + n\beta^2 \right) [g(\mathcal{B}_2, \mathcal{B}_3) \mathcal{V}^\flat(\mathcal{B}_1) + g(\mathcal{B}_2, \mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_3) - 2\mathcal{V}^\flat(\mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_2) \mathcal{V}^\flat(\mathcal{B}_3)], \end{aligned} \quad (8.3)$$

and

$$\begin{aligned} (\nabla_{\mathcal{B}_3} S)(\mathcal{B}_1, \mathcal{B}_2) &= \frac{dr(\mathcal{B}_3)}{n-1} \left\{ g(\mathcal{B}_1, \mathcal{B}_2) + \mathcal{V}^\flat(\mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_2) \right\} \\ &\quad + \beta \left(\frac{r}{n-1} + n\beta^2 \right) [g(\mathcal{B}_3, \mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_2) + g(\mathcal{B}_3, \mathcal{B}_2) \mathcal{V}^\flat(\mathcal{B}_1) - 2\mathcal{V}^\flat(\mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_2) \mathcal{V}^\flat(\mathcal{B}_3)]. \end{aligned} \quad (8.4)$$

Cartan hypersurfaces are recognized as manifolds with a non-parallel Ricci tensor that satisfies equation (8.1). From this equation, we can deduce that r is constant. Considering equations (8.2)-(8.4) in relation to (8.1), we obtain

$$\beta \left(\frac{r}{n-1} + n\beta^2 \right) [g(\mathcal{B}_1, \mathcal{B}_2) \mathcal{V}^\flat(\mathcal{B}_3) + g(\mathcal{B}_2, \mathcal{B}_3) \mathcal{V}^\flat(\mathcal{B}_1) + g(\mathcal{B}_3, \mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_2) - 3\mathcal{V}^\flat(\mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_2) \mathcal{V}^\flat(\mathcal{B}_3)] = 0. \quad (8.5)$$

Replacing $\mathcal{B}_1$ by $\phi\mathcal{B}_1$ in (8.5) and applying (2.2), we achieve

$$\beta \left(\frac{r}{n-1} + n\beta^2 \right) [g(\phi\mathcal{B}_1, \mathcal{B}_2) \mathcal{V}^\flat(\mathcal{B}_3) + g(\mathcal{B}_3, \phi\mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_2)] = 0. \quad (8.6)$$

Plugging $\mathcal{B}_3 = \zeta$ in (8.6) and using (2.2), it gives

$$\beta \left(\frac{r}{n-1} + n\beta^2 \right) g(\phi\mathcal{B}_1, \mathcal{B}_2) = 0. \quad (8.7)$$

Thus, we get

$$r = -n(n-1)\beta^2.$$

This results in the following:

Theorem 8.1 *If an $\mathcal{M}_\beta$ possesses a cyclic parallel Ricci tensor, the scalar curvature of the manifold remains constant at $-n(n-1)\beta^2$.*

9 $\mathcal{V}^\flat$ -Parallel Ricci Tensor

Kon [15] introduced the concept of $\mathcal{V}^\flat$ -parallel Ricci tensor for an $\mathcal{M}_\beta$.

Definition 9.1 *An $\mathcal{M}_\beta$ is called $\mathcal{V}^\flat$ -parallel if it's Ricci tensor S satisfies*

$$(\nabla_{\mathcal{B}_3} S)(\phi\mathcal{B}_1, \phi\mathcal{B}_2) = 0, \quad (9.1)$$

holds for $\mathcal{B}_1, \mathcal{B}_2, \mathcal{B}_3 \in \chi(\mathcal{M}_\beta)$.

Let us assume that the Ricci tensor of a $\mathcal{M}_\beta$ is $\mathcal{V}^\flat$ -parallel, then (9.1) holds. From (2.19), we can easily find that

$$S(\varphi \mathcal{B}_1, \varphi \mathcal{B}_2) = \left(\frac{r}{n-1} + \beta^2 \right) g(\varphi \mathcal{B}_1, \varphi \mathcal{B}_2). \quad (9.2)$$

By utilizing (2.3) and applying the covariant derivative to (9.2) w.r.t. any vector field $\mathcal{B}_3$, we derive

$$\begin{aligned} (\nabla_{\mathcal{B}_3} S)(\varphi \mathcal{B}_1, \varphi \mathcal{B}_2) &= \frac{dr(\mathcal{B}_3)}{n-1} \left\{ g(\mathcal{B}_1, \mathcal{B}_2) + \mathcal{V}^\flat(\mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_2) \right\} \\ &\quad + \beta \left(\frac{r}{n-1} + \beta^2 \right) [(\nabla_{\mathcal{B}_3} \mathcal{V}^\flat)(\mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_2) + (\nabla_{\mathcal{B}_3} \mathcal{V}^\flat)(\mathcal{B}_2) \mathcal{V}^\flat(\mathcal{B}_1)]. \end{aligned} \quad (9.3)$$

In view of (2.6) in (9.3), we have

$$\begin{aligned} (\nabla_{\mathcal{B}_3} S)(\varphi \mathcal{B}_1, \varphi \mathcal{B}_2) &= \frac{dr(\mathcal{B}_3)}{n-1} \left\{ g(\mathcal{B}_1, \mathcal{B}_2) + \mathcal{V}^\flat(\mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_2) \right\} \\ &\quad + \beta \left(\frac{r}{n-1} + \beta^2 \right) [g(\mathcal{B}_3, \mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_2) + g(\mathcal{B}_3, \mathcal{B}_2) \mathcal{V}^\flat(\mathcal{B}_1) - 2 \mathcal{V}^\flat(\mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_2) \mathcal{V}^\flat(\mathcal{B}_3)]. \end{aligned} \quad (9.4)$$

Thus, (9.1) and (9.4) together give

$$\begin{aligned} \frac{dr(\mathcal{B}_3)}{n-1} \left\{ g(\mathcal{B}_1, \mathcal{B}_2) + \mathcal{V}^\flat(\mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_2) \right\} &+ \beta \left(\frac{r}{n-1} + \beta^2 \right) [g(\mathcal{B}_3, \mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_2) + g(\mathcal{B}_3, \mathcal{B}_2) \mathcal{V}^\flat(\mathcal{B}_1) \\ &\quad - 2 \mathcal{V}^\flat(\mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_2) \mathcal{V}^\flat(\mathcal{B}_3)] = 0. \end{aligned} \quad (9.5)$$

Consider an orthonormal frame field $\{e_i\}_{i=1}^n$ defined at any point of $\mathcal{M}_\beta$. By substituting $\mathcal{B}_1 = \mathcal{B}_2 = e_i$ in (9.5) and performing contraction, we obtain

$$dr(\mathcal{B}_3) = -4\beta \left(\frac{r}{n-1} + \beta^2 \right) \mathcal{V}^\flat(\mathcal{B}_3). \quad (9.6)$$

Using this in (9.5), we obtain

$$\beta \left(\frac{r}{n-1} + \beta^2 \right) \left[g(\mathcal{B}_3, \mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_2) + g(\mathcal{B}_3, \mathcal{B}_2) \mathcal{V}^\flat(\mathcal{B}_1) - 4g(\mathcal{B}_1, \mathcal{B}_2) \mathcal{V}^\flat(\mathcal{B}_3) - 6 \mathcal{V}^\flat(\mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_2) \mathcal{V}^\flat(\mathcal{B}_3) \right] = 0. \quad (9.7)$$

Replacing $\mathcal{B}_1$ by ζ in the above equation, it yields

$$\beta \left(\frac{r}{n-1} + \beta^2 \right) [3 \mathcal{V}^\flat(\mathcal{B}_2) \mathcal{V}^\flat(\mathcal{B}_3) - g(\mathcal{B}_2, \mathcal{B}_3)] = 0. \quad (9.8)$$

Since, $3 \mathcal{V}^\flat(\mathcal{B}_2) \mathcal{V}^\flat(\mathcal{B}_3) - g(\mathcal{B}_2, \mathcal{B}_3) \neq 0$, therefore

$$r = -(n-1)\beta^2. \quad (9.9)$$

Conversely, if $r = -(n-1)\beta^2$, one can easily find from (9.4) that

$$(\nabla_{\mathcal{B}_3} S)(\varphi \mathcal{B}_1, \varphi \mathcal{B}_2) = 0, \quad (9.10)$$

for all $\mathcal{B}_1, \mathcal{B}_2, \mathcal{B}_3 \in \mathcal{X}(\mathcal{M}_\beta)$.

Hence, we arrive at the following conclusion:

Theorem 9.1 An n -dimensional $\mathcal{M}_\beta$ is $\mathcal{V}^\flat$ -parallel Ricci tensor iff $\mathcal{M}_\beta$ has constant scalar curvature $-(n-1)\beta^2$.

10 Ricci-Bourguignon Soliton

Assume that an $\mathcal{M}_\beta$ possesses an RB soliton with the potential vector field being the Reeb vector field ζ . From equation (1.3), we then obtain

$$\xi_\zeta g(\mathcal{B}_1, \mathcal{B}_2) + 2S(\mathcal{B}_1, \mathcal{B}_2) = 2\Lambda g(\mathcal{B}_1, \mathcal{B}_2) + 2\psi r g(\mathcal{B}_1, \mathcal{B}_2), \quad (10.1)$$

which gives

$$g(\nabla_{\mathcal{B}_1} \zeta, \mathcal{B}_2) + g(\nabla_{\mathcal{B}_2} \zeta, \mathcal{B}_1) + 2S(\mathcal{B}_1, \mathcal{B}_2) = 2\Lambda g(\mathcal{B}_1, \mathcal{B}_2) + 2\psi r g(\mathcal{B}_1, \mathcal{B}_2). \quad (10.2)$$

Taking into account of (2.5), the above expression takes the form

$$S(\mathcal{B}_1, \mathcal{B}_2) = [\Lambda + \psi r - \beta]g(\mathcal{B}_1, \mathcal{B}_2) + \beta \mathcal{V}^\flat(\mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_2). \quad (10.3)$$

Plugging $\mathcal{B}_2 = \zeta$ in (10.3) and making use of (2.1) and (2.10), we achieve

$$[2\beta - (n-1)\beta^2 - \Lambda - \psi r] \mathcal{V}^\flat(\mathcal{B}_1) = 0. \quad (10.4)$$

Since $\mathcal{V}^\flat(\mathcal{B}_1) \neq 0$, then it follows that

$$\Lambda = 2\beta - (n-1)\beta^2 - \psi r. \quad (10.5)$$

Hence, we reach to the following:

Theorem 10.1 For an n -dimensional $\mathcal{M}_\beta$ with metric g that fulfills the RB soliton $(g, \zeta, \Lambda, \psi)$, where ζ represents the reeb vector field, then the soliton's nature is shrinking, steady, expanding accordingly $2\beta - (n-1)\beta^2 - \psi r \gtrless 0$.

We incorporate the identity from (10.5) into (10.3) to acquire

$$S(\mathcal{B}_1, \mathcal{B}_2) = [\beta - (n-1)\beta^2]g(\mathcal{B}_1, \mathcal{B}_2) + \beta \mathcal{V}^\flat(\mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_2). \quad (10.6)$$

Let $\{e_i\}_{i=1}^n$ be an orthonormal frame field at any point of $\mathcal{M}_\beta$. If we set $\mathcal{B}_1 = \mathcal{B}_2 = e_i$ in (10.6) and sum over i , $1 \leq i \leq n$, we have

$$r = -(n-1)(n\beta - 1)\beta. \quad (10.7)$$

Hence, we reach at the following conclusion:

Theorem 10.2 If an n -dimensional $\mathcal{M}_\beta$ admits an RB soliton $(g, \zeta, \Lambda, \psi)$ whose potential vector field is the Reeb vector field ζ , then the manifold becomes an $\mathcal{V}^\flat$ -Einstein manifold and the scalar curvature is of the form $r = -(n-1)(n\beta - 1)\beta$.

11 Example of a five-dimensional $\mathcal{M}_\beta$

Consider a five dimensional manifold $\mathcal{M}^5 = \{(\vartheta_1, \vartheta_2, \vartheta_3, \vartheta_4, \vartheta_5) \in \mathbb{R}^5 : \vartheta_5 \neq 0\}$, where $(\vartheta_1, \vartheta_2, \vartheta_3, \vartheta_4, \vartheta_5)$ are the standard coordinates in $\mathbb{R}^5$. We choose

$$\rho_1 = \cos^2 \vartheta_5 \frac{\partial}{\partial \vartheta_1}, \quad \rho_2 = \cos^2 \vartheta_5 \frac{\partial}{\partial \vartheta_2}, \quad \rho_3 = \cos^2 \vartheta_5 \frac{\partial}{\partial \vartheta_3}, \quad \rho_4 = \cos^2 \vartheta_5 \frac{\partial}{\partial \vartheta_4},$$

$$\rho_5 = \vartheta_1 \frac{\partial}{\partial \vartheta_1} + \vartheta_2 \frac{\partial}{\partial \vartheta_2} + \vartheta_3 \frac{\partial}{\partial \vartheta_3} + \vartheta_4 \frac{\partial}{\partial \vartheta_4} + \frac{\partial}{\partial \vartheta_5},$$

which are linearly independent at each point of the manifold $\mathcal{M}^5$.

Let the Lorentzian metric g be defined by

$$g(\rho_m, \rho_n) = \begin{cases} 1, & \text{if } m = n \text{ and } m, n \in \{1, 2, 3, 4\}, \\ -1, & \text{if } m = n = 5, \\ 0, & \text{otherwise.} \end{cases}$$

Let the 1-form $\mathcal{V}^\flat$ satisfy the relation

$$\mathcal{V}^\flat(\rho_5) = -1.$$

Let a $(1, 1)$ tensor field ϕ be given by $\phi(\rho_1) = -\rho_2$, $\phi(\rho_3) = -\rho_4$, $\phi(\rho_5) = 0$. Then, we have

$$\phi^2(\mathcal{B}_1) = \mathcal{B}_1 + \mathcal{V}^\flat(\mathcal{B}_1)\zeta,$$

$$g(\phi \mathcal{B}_1, \phi \mathcal{B}_2) = g(\mathcal{B}_1, \mathcal{B}_2) + \mathcal{V}^\flat(\mathcal{B}_1) \mathcal{V}^\flat(\mathcal{B}_2),$$

for any $\mathcal{B}_1, \mathcal{B}_2 \in \chi(\mathcal{M}^5)$. Thus for $\rho_5 = \zeta$, $\mathcal{M}^5(\varphi, \zeta, \mathcal{V}^b, g)$ defines an *almost contact metric structure* on $\mathcal{M}^5$. Now, we have

$$\begin{aligned} [\rho_1, \rho_2] &= 0, & [\rho_1, \rho_3] &= 0, & [\rho_1, \rho_4] &= 0, & [\rho_1, \rho_5] &= (1 - 2 \tan \vartheta_5) \rho_1, \\ [\rho_2, \rho_3] &= 0, & [\rho_2, \rho_4] &= 0, & [\rho_2, \rho_5] &= (1 - 2 \tan \vartheta_5) \rho_2, & [\rho_3, \rho_4] &= 0, \\ & & [\rho_3, \rho_5] &= (1 - 2 \tan \vartheta_5) \rho_3, & [\rho_4, \rho_5] &= (1 - 2 \tan \vartheta_5) \rho_4. \end{aligned}$$

Setting $\rho_5 = \zeta$ and using well known Koszul's formula, we arrive at the following:

$$\begin{cases} \nabla_{\rho_1} \rho_1 = -(1 - 2 \tan \vartheta_5) \rho_1, & \nabla_{\rho_2} \rho_1 = 0, & \nabla_{\rho_3} \rho_1 = 0, & \nabla_{\rho_4} \rho_1 = 0, & \nabla_{\rho_5} \rho_1 = 0, \\ \nabla_{\rho_1} \rho_2 = 0, & \nabla_{\rho_2} \rho_2 = -(1 - 2 \tan \vartheta_5) \rho_2, & \nabla_{\rho_3} \rho_2 = 0, & \nabla_{\rho_4} \rho_2 = 0, & \nabla_{\rho_5} \rho_2 = 0, \\ \nabla_{\rho_1} \rho_3 = \rho_1, & \nabla_{\rho_2} \rho_3 = \rho_2, & \nabla_{\rho_3} \rho_3 = -(1 - 2 \tan \vartheta_5) \rho_3, & \nabla_{\rho_4} \rho_3 = 0, & \nabla_{\rho_5} \rho_3 = 0, \\ \nabla_{\rho_1} \rho_4 = \rho_1, & \nabla_{\rho_2} \rho_4 = \rho_2, & \nabla_{\rho_3} \rho_4 = 0, & \nabla_{\rho_4} \rho_4 = -(1 - 2 \tan \vartheta_5) \rho_4, & \nabla_{\rho_5} \rho_4 = 0, \\ \nabla_{\rho_1} \rho_5 = (1 - 2 \tan \vartheta_5) \rho_1, & \nabla_{\rho_2} \rho_5 = (1 - 2 \tan \vartheta_5) \rho_2, & \nabla_{\rho_3} \rho_5 = (1 - 2 \tan \vartheta_5) \rho_3, \\ \nabla_{\rho_4} \rho_5 = (1 - 2 \tan \vartheta_5) \rho_4, & \nabla_{\rho_5} \rho_5 = 0. \end{cases}$$

Hence we can see that for $\beta = (1 - 2 \tan \vartheta_5)$, $\mathcal{M}^5(\varphi, \zeta, \mathcal{V}^b, g)$ is an $\mathcal{M}_\beta$ of dimension 5. The components of the curvature tensor with respect to ∇ are as follows

$$\begin{cases} R(\rho_1, \rho_2) \rho_2 = -\beta^2 \rho_1, & R(\rho_1, \rho_5) \rho_5 = \beta^2 \rho_1, & R(\rho_1, \rho_4) \rho_1 = \beta^2 \rho_4, & R(\rho_2, \rho_4) \rho_2 = \beta^2 \rho_4, \\ R(\rho_2, \rho_4) \rho_4 = -\beta^2 \rho_2, & R(\rho_3, \rho_5) \rho_3 = \beta^2 \rho_5, & R(\rho_1, \rho_3) \rho_3 = -\beta^2 \rho_1, & R(\rho_1, \rho_2) \rho_1 = \beta^2 \rho_2, \\ R(\rho_1, \rho_5) \rho_1 = \beta^2 \rho_5, & R(\rho_2, \rho_5) \rho_2 = \beta^2 \rho_5, & R(\rho_2, \rho_5) \rho_5 = \beta^2 \rho_2, & R(\rho_3, \rho_4) \rho_4 = -\beta^2 \rho_3, \\ R(\rho_4, \rho_5) \rho_5 = \beta^2 \rho_4, & R(\rho_1, \rho_4) \rho_4 = -\beta^2 \rho_1, & R(\rho_1, \rho_3) \rho_1 = \beta^2 \rho_3, & R(\rho_2, \rho_3) \rho_2 = \beta^2 \rho_3, \\ R(\rho_2, \rho_3) \rho_3 = -\beta^2 \rho_2, & R(\rho_3, \rho_4) \rho_3 = \beta^2 \rho_4, & R(\rho_4, \rho_5) \rho_4 = \beta^2 \rho_5, & R(\rho_3, \rho_5) \rho_5 = \beta^2 \rho_3. \end{cases}$$

From above, we can obtain

$$S(\rho_1, \rho_1) = -4\beta^2, \quad S(\rho_2, \rho_2) = -4\beta^2, \quad S(\rho_3, \rho_3) = -4\beta^2, \quad S(\rho_4, \rho_4) = -4\beta^2, \quad S(\rho_5, \rho_5) = -4\beta^2.$$

$$\Rightarrow \quad r = \sum_{i=1}^5 S(\rho_i, \rho_i) = -20\beta^2.$$

Declarations

Competing interests: The authors affirm that they do not have any competing interests related to this research article.

Authors' contributions: All authors contributed equally in the preparation of this manuscript.

Funding: There is no financial support for the research by any organizations or institutions.

Availability of data and materials: Not Applicable.

Acknowledgments: The authors wish to express their sincere thanks and gratitude to the anonymous editor /referee for his/her valuable suggestions toward the improvement of the paper.

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